

On a family of frames for Krein spaces

J. I. Giribet, A. Maestripieri, F. Martínez Pería and P. Massey

Abstract

A definition of frames for Krein spaces is proposed, which extends the notion of J -orthonormal basis of Krein spaces. A J -frame for a Krein space $(\mathcal{H}, [\cdot, \cdot])$ is in particular a frame for \mathcal{H} in the Hilbert space sense. But it is also compatible with the indefinite inner product $[\cdot, \cdot]$, meaning that it determines a pair of maximal uniformly J -definite subspaces with different positivity, an analogue to the maximal dual pair associated to a J -orthonormal basis.

Also, each J -frame induces an indefinite reconstruction formula for the vectors in \mathcal{H} , which resembles the one given by a J -orthonormal basis.

keywords: Krein spaces, frames, uniformly J -definite subspaces

MSC 2000: 46C20, 47B50, 42C15

1 Introduction

In recent years, frame theory for Hilbert spaces has been thoroughly developed, see e. g. [6, 8, 9, 16]. Fixed a Hilbert space $(\mathcal{H}, \langle \cdot, \cdot \rangle)$, a frame for \mathcal{H} is a (generally overcomplete) family of vectors $\mathcal{F} = \{f_i\}_{i \in I}$ in \mathcal{H} which satisfies the inequalities

$$A\|f\|^2 \leq \sum_{i \in I} |\langle f, f_i \rangle|^2 \leq B\|f\|^2, \quad \text{for every } f \in \mathcal{H}, \quad (1)$$

for positive constants $0 < A \leq B$. The (bounded, linear) operator $S : \mathcal{H} \rightarrow \mathcal{H}$ defined by

$$Sf = \sum_{i \in I} \langle f, f_i \rangle f_i, \quad f \in \mathcal{H}, \quad (2)$$

is known as the frame operator associated to \mathcal{F} . The inequalities in Eq. (1) imply that S is a (positive) boundedly invertible operator, and it allows to reconstruct each vector $f \in \mathcal{H}$ in terms of the family \mathcal{F} as follows:

$$f = \sum_{i \in I} \langle f, S^{-1} f_i \rangle f_i = \sum_{i \in I} \langle f, f_i \rangle S^{-1} f_i. \quad (3)$$

The above formula is known as the *reconstruction formula associated to \mathcal{F}* . Notice that if \mathcal{F} is a Parseval frame, i.e. if $S = I$, then the reconstruction formula resembles the Fourier series of f associated to an orthonormal basis $\mathcal{B} = \{b_k\}_{k \in K}$ of \mathcal{H} :

$$f = \sum_{k \in K} \langle f, b_k \rangle b_k,$$

but the *frame coefficients* $\{\langle f, f_i \rangle\}_{i \in I}$ given by \mathcal{F} allow to reconstruct f even when some of these coefficients are missing (or corrupted). Indeed, each vector $f \in \mathcal{H}$ may admit several reconstructions in terms of the frame coefficients as a consequence of the redundancy of \mathcal{F} . These are some of the advantages of frames over (orthonormal, orthogonal or Riesz) bases in signal processing applications, when noisy channels are involved, e.g. see [3, 17, 22].

Given a Krein space $(\mathcal{H}, [\cdot, \cdot])$ with fundamental symmetry J , a J -orthonormalized system is a family $\mathcal{E} = \{e_i\}_{i \in I}$ such that $[e_i, e_j] = \pm \delta_{ij}$, for $i, j \in I$. A J -orthonormal basis is a J -orthonormalized system which is also a Schauder basis for \mathcal{H} . If $\mathcal{E} = \{e_i\}_{i \in I}$ is a J -orthonormal basis of \mathcal{H} then the vectors in \mathcal{H} can be represented as follows:

$$f = \sum_{i \in I} \sigma_i [f, e_i] e_i, \quad f \in \mathcal{H}, \quad (4)$$

where $\sigma_i = [e_i, e_i] = \pm 1$.

J -orthonormalized systems (and bases) are intimately related to the notion of dual pair. In fact, each J -orthonormalized system generates a *dual pair*, i.e. a pair $(\mathcal{L}_+, \mathcal{L}_-)$ of subspaces of \mathcal{H} such that \mathcal{L}_+ is J -nonnegative, \mathcal{L}_- is J -nonpositive and \mathcal{L}_+ is J -orthogonal to \mathcal{L}_- , i.e. $[\mathcal{L}_+, \mathcal{L}_-] = 0$. Moreover, if \mathcal{E} is a J -orthonormal basis of \mathcal{H} , the dual pair associated to \mathcal{E} is maximal (with respect to the inclusion preorder) and the subspaces \mathcal{L}_+ and \mathcal{L}_- are uniformly J -definite, see [18, Ch.1, §10]. Therefore the dual pair $(\mathcal{L}_+, \mathcal{L}_-)$ is a fundamental decomposition of \mathcal{H} . Notice that, considering the Hilbert space structure induced by the above fundamental decomposition, the J -orthonormal basis \mathcal{E} turns out to be an orthonormal basis in the associated Hilbert space. Therefore, each J -orthonormal basis can be realized as an orthonormal basis of \mathcal{H} (respect to an appropriate definite inner product).

Given a pair of maximal uniformly J -definite subspaces \mathcal{M}_+ and \mathcal{M}_- of a Krein space \mathcal{H} , with different positivity, if $\mathcal{F}_\pm = \{f_i\}_{i \in I_\pm}$ is a frame for the Hilbert space $(\mathcal{M}_\pm, \pm[\cdot, \cdot])$, it is easy to see that

$$\mathcal{F} = \mathcal{F}_+ \cup \mathcal{F}_-,$$

is a frame for \mathcal{H} , which produces an *indefinite reconstruction formula*:

$$f = \sum_{i \in I} \sigma_i [f, g_i] f_i = \sum_{i \in I} \sigma_i [f, f_i] g_i, \quad f \in \mathcal{H},$$

where $\sigma_i = \text{sgn}[f_i, f_i]$ and $\{g_i\}_{i \in I}$ is some (equivalent) frame for \mathcal{H} (see Example 2 and Proposition 5.3).

The aim of this work is to introduce and characterize a particular family of frames for a Krein space $(\mathcal{H}, [\cdot, \cdot])$ -hereafter called J -frames- that are compatible with the indefinite inner product $[\cdot, \cdot]$. Some different approaches to frames for Krein spaces and indefinite reconstruction formulas are developed in [14] and [21], respectively.

The paper is organized as follows: Section 2 contains some preliminaries results both in Krein spaces and in frame theory for Hilbert spaces.

Section 3 presents the J -frames. Briefly, a J -frame for the Krein space $(\mathcal{H}, [\cdot, \cdot])$ is a Bessel family $\mathcal{F} = \{f_i\}_{i \in I}$ with synthesis operator $T : \ell_2(I) \rightarrow \mathcal{H}$ such that the ranges of $T_+ := TP_+$ and $T_- := T(I - P_+)$ are maximal uniformly J -positive and maximal uniformly J -negative subspaces, respectively, where $I_+ = \{i \in I : [f_i, f_i] > 0\}$ and P_+ is the orthogonal projection onto $\ell_2(I_+)$, as a subspace of $\ell_2(I)$.

It is immediate that J -orthonormal bases are J -frames, because they generate maximal dual pairs [18, Ch. 1, §10.12].

Also, if \mathcal{F} is a J -frame for \mathcal{H} , observe that $R(T) = R(T_+) + R(T_-)$ and recall that the sum of a pair of maximal uniformly J -definite subspaces with different positivity coincides with \mathcal{H} [2, Corollary 1.5.2]. Therefore, each J -frame is in fact a frame for \mathcal{H} in the Hilbert space sense. Moreover, it is shown that $\mathcal{F}_+ = \{f_i\}_{i \in I_+}$ is a frame for the Hilbert space $(R(T_+), [\cdot, \cdot])$ and $\mathcal{F}_- = \{f_i\}_{i \in I \setminus I_+}$ is a frame for $(R(T_-), -[\cdot, \cdot])$, i.e. there exist constants $B_- \leq A_- < 0 < A_+ \leq B_+$ such that

$$A_\pm [f, f] \leq \sum_{i \in I_\pm} |[f, f_i]|^2 \leq B_\pm [f, f] \quad \text{for every } f \in R(T_\pm). \quad (5)$$

The optimal constants satisfying the above inequalities can be characterized in terms of T_\pm and the Gramian operators of their ranges.

This section ends with a geometrical characterization of J -frames, in terms of the (minimal) angles between the uniformly J -definite subspace $R(T_\pm)$ and the cone of neutral vectors of the Krein space.

Section 4 is devoted to study the synthesis operators associated to J -frames. Fixed a Krein space \mathcal{H} and given a bounded operator $T : \ell_2(I) \rightarrow \mathcal{H}$, it is described under which conditions T is the synthesis operator of a J -frame.

In Section 5 the J -frame operator is introduced. Given a J -frame $\mathcal{F} = \{f_i\}_{i \in I}$, the J -frame operator $S : \mathcal{H} \rightarrow \mathcal{H}$ is defined by

$$Sf = \sum_{i \in I} \sigma_i [f, f_i] f_i, \quad f \in \mathcal{H},$$

where $\sigma_i = \text{sgn}([f_i, f_i])$. This operator resembles the frame operator for frames in Hilbert spaces (see Eq. (2)), and it has similar properties, in particular $S = TT^\#$ if $T : \ell_2(I) \rightarrow \mathcal{H}$ is the synthesis operator of

\mathcal{F} (see Proposition 5.1). Furthermore, each J -frame $\mathcal{F} = \{f_i\}_{i \in I}$ determines an *indefinite reconstruction formula*, which depends on the J -frame operator S :

$$f = \sum_{i \in I} \sigma_i [f, S^{-1}f_i] f_i = \sum_{i \in I} \sigma_i [f, f_i] S^{-1}f_i, \quad \text{for every } f \in \mathcal{H}. \quad (6)$$

In this case the family $\{S^{-1}f_i\}_{i \in I}$ turns out to be a J -frame too.

Finally, it will be shown that the J -frame operator of a J -frame \mathcal{F} is intimately related to the projection $Q = P_{R(T_+)/R(T_-)}$ determined by the decomposition $\mathcal{H} = R(T_+) \dot{+} R(T_-)$. In fact, fixed a J -selfadjoint invertible operator S acting on a Krein space \mathcal{H} , it is the J -frame operator for a J -frame \mathcal{F} if and only if there exists a projection Q with uniformly J -definite range and kernel such that QS is a J -positive operator and $(I - Q)S$ is a J -negative operator, see Theorem 5.5.

2 Preliminaries

Along this work \mathcal{H} denotes a complex (separable) Hilbert space. If \mathcal{K} is another Hilbert space then $L(\mathcal{H}, \mathcal{K})$ is the algebra of bounded linear operators from \mathcal{H} into \mathcal{K} and $L(\mathcal{H}) = L(\mathcal{H}, \mathcal{H})$. The groups of linear invertible and unitary operators acting on \mathcal{H} are denoted by $GL(\mathcal{H})$ and $\mathcal{U}(\mathcal{H})$, respectively. Also, $L(\mathcal{H})^+$ denotes the cone of positive semidefinite operators acting on \mathcal{H} and $GL(\mathcal{H})^+ = GL(\mathcal{H}) \cap L(\mathcal{H})^+$.

If $T \in L(\mathcal{H}, \mathcal{K})$ then $T^* \in L(\mathcal{K}, \mathcal{H})$ denotes the adjoint operator of T , $R(T)$ stands for its range and $N(T)$ for its nullspace. Also, if $T \in L(\mathcal{H}, \mathcal{K})$ has closed range, $T^\dagger \in L(\mathcal{K}, \mathcal{H})$ denotes the Moore-Penrose inverse of T .

Hereafter, $\mathcal{S} \dot{+} \mathcal{T}$ denotes the direct sum of two (closed) subspaces \mathcal{S} and \mathcal{T} of \mathcal{H} . On the other hand, $\mathcal{S} \oplus \mathcal{T}$ stands for the (direct) orthogonal sum of them and $\mathcal{S} \ominus \mathcal{T} := \mathcal{S} \cap (\mathcal{S} \cap \mathcal{T})^\perp$. If $\mathcal{H} = \mathcal{S} \dot{+} \mathcal{T}$, the oblique projection onto \mathcal{S} along \mathcal{T} is the unique projection with range \mathcal{S} and nullspace \mathcal{T} . It is denoted by $P_{\mathcal{S}/\mathcal{T}}$. In particular, $P_{\mathcal{S}} := P_{\mathcal{S}/\mathcal{S}^\perp}$ is the orthogonal projection onto \mathcal{S} .

2.1 Krein spaces

In what follows we present the standard notation and some basic results on Krein spaces. For a complete exposition on the subject (and the proofs of the results below) see the books by J. Bognár [4] and T. Ya. Azizov and I. S. Iokhvidov [18] and the monographs by T. Ando [2] and by M. Dritschel and J. Rovnyak [13].

Given a Krein space $(\mathcal{H}, [\cdot, \cdot])$ with a *fundamental decomposition* $\mathcal{H} = \mathcal{H}_+ \dot{+} \mathcal{H}_-$, the direct (orthogonal) sum of the Hilbert spaces $(\mathcal{H}_+, [\cdot, \cdot])$ and $(\mathcal{H}_-, -[\cdot, \cdot])$ is denoted by $(\mathcal{H}, \langle \cdot, \cdot \rangle)$.

Observe that the indefinite metric and the inner product of \mathcal{H} are related by means of a *fundamental symmetry*, i.e. a unitary selfadjoint operator $J \in L(\mathcal{H})$ which satisfies:

$$[x, y] = \langle Jx, y \rangle, \quad x, y \in \mathcal{H}.$$

If \mathcal{H} and \mathcal{K} are Krein spaces, $L(\mathcal{H}, \mathcal{K})$ stands for the vector space of linear transformations which are bounded respect to the associated Hilbert spaces $(\mathcal{H}, \langle \cdot, \cdot \rangle_{\mathcal{H}})$ and $(\mathcal{K}, \langle \cdot, \cdot \rangle_{\mathcal{K}})$. Given $T \in L(\mathcal{H}, \mathcal{K})$, the J -adjoint operator of T is defined by $T^\# = J_{\mathcal{H}}T^*J_{\mathcal{K}}$, where $J_{\mathcal{H}}$ and $J_{\mathcal{K}}$ are the fundamental symmetries associated to \mathcal{H} and \mathcal{K} , respectively. An operator $T \in L(\mathcal{H})$ is J -selfadjoint if $T = T^\#$.

A vector $x \in \mathcal{H}$ is J -positive if $[x, x] > 0$. A subspace \mathcal{S} of \mathcal{H} is J -positive if every $x \in \mathcal{S}$, $x \neq 0$, is a J -positive vector. A subspace \mathcal{S} of \mathcal{H} is *uniformly J -positive* if there exists $\alpha > 0$ such that

$$[x, x] \geq \alpha \|x\|^2, \quad \text{for every } x \in \mathcal{S},$$

where $\|\cdot\|$ stands for the norm of the associated Hilbert space $(\mathcal{H}, \langle \cdot, \cdot \rangle)$.

J -nonnegative, J -neutral, J -negative, J -nonpositive and uniformly J -negative vectors and subspaces are defined analogously.

Remark 2.1. If \mathcal{S}_+ is a closed uniformly J -positive subspace of a Krein space $(\mathcal{H}, [\cdot, \cdot])$, observe that $(\mathcal{S}_+, [\cdot, \cdot])$ is a Hilbert space. In fact, the forms $[\cdot, \cdot]$ and $\langle \cdot, \cdot \rangle$ are equivalent inner products on \mathcal{S}_+ , because

$$\alpha \|f\|^2 \leq [f, f] \leq \|f\|^2, \quad \text{for every } f \in \mathcal{S}_+.$$

Analogously, if \mathcal{S}_- is a closed uniformly J -negative subspace of $(\mathcal{H}, [\cdot, \cdot])$, $(\mathcal{S}_-, -[\cdot, \cdot])$ is a Hilbert space.

Proposition 2.2 ([18], Cor. 7.17). *Let \mathcal{H} be a Krein space with fundamental symmetry J and \mathcal{S} a J -nonnegative closed subspace of \mathcal{H} . Then, \mathcal{S} is the range of a J -selfadjoint projection if and only if \mathcal{S} is uniformly J -positive.*

Recall that, given a closed subspace \mathcal{M} of a Krein space \mathcal{H} , the Gramian operator of \mathcal{M} is defined by:

$$G_{\mathcal{M}} = P_{\mathcal{M}} J P_{\mathcal{M}},$$

where $P_{\mathcal{M}}$ is the orthogonal projection onto \mathcal{M} and J is the fundamental symmetry of \mathcal{H} . If \mathcal{M} is J -semidefinite, then $\mathcal{M} \cap \mathcal{M}^{[\perp]}$ coincides with $\mathcal{N} := \{f \in \mathcal{M} : [f, f] = 0\}$. Therefore, it is easy to see that

$$G_{\mathcal{M}} = G_{\mathcal{M} \ominus \mathcal{N}}.$$

Given a subspace \mathcal{S} of a Krein space \mathcal{H} , the J -orthogonal companion to \mathcal{S} is defined by

$$\mathcal{S}^{[\perp]} = \{x \in \mathcal{H} : [x, s] = 0 \text{ for every } s \in \mathcal{S}\}.$$

A subspace \mathcal{S} of \mathcal{H} is J -non degenerated if $\mathcal{S} \cap \mathcal{S}^{[\perp]} = \{0\}$. Notice that if \mathcal{S} is a J -definite subspace of \mathcal{H} then it is J -non degenerated.

2.2 Angles between subspaces and reduced minimum modulus

Given two closed subspaces \mathcal{S} and \mathcal{T} of a Hilbert space \mathcal{H} , the cosine of the *Friedrichs angle* between \mathcal{S} and \mathcal{T} is defined by

$$c(\mathcal{S}, \mathcal{T}) = \sup\{|\langle x, y \rangle| : x \in \mathcal{S} \ominus \mathcal{T}, \|x\| = 1, y \in \mathcal{T} \ominus \mathcal{S}, \|y\| = 1\}.$$

It is well known that

$$c(\mathcal{S}, \mathcal{T}) < 1 \Leftrightarrow \mathcal{S} + \mathcal{T} \text{ is closed} \Leftrightarrow c(\mathcal{S}^\perp, \mathcal{T}^\perp) < 1.$$

Furthermore, if $P_{\mathcal{S}}$ and $P_{\mathcal{T}}$ are the orthogonal projections onto \mathcal{S} and \mathcal{T} , respectively, then $c(\mathcal{S}, \mathcal{T}) < 1$ if and only if $(I - P_{\mathcal{S}})P_{\mathcal{T}}$ has closed range. See [10] for further details.

The next definition is due to T. Kato, see [19, Ch. IV, § 5].

Definition. The *reduced minimum modulus* $\gamma(T)$ of an operator $T \in L(\mathcal{H}, \mathcal{K})$ is defined by

$$\gamma(T) = \inf\{\|Tx\| : x \in N(T)^\perp, \|x\| = 1\}.$$

Observe that $\gamma(T) = \sup\{C \geq 0 : C\|x\| \leq \|Tx\| \text{ for every } x \in N(T)^\perp, \|x\| = 1\}$. It is well known that $\gamma(T) = \gamma(T^*) = \gamma(T^*T)^{1/2}$. Also, it can be shown that an operator $T \neq 0$ has closed range if and only if $\gamma(T) > 0$. In this case, $\gamma(T) = \|T^\dagger\|^{-1}$.

If \mathcal{H} and \mathcal{K} are Krein spaces with fundamental symmetries $J_{\mathcal{H}}$ and $J_{\mathcal{K}}$, respectively, and $T \in L(\mathcal{H}, \mathcal{K})$ then

$$\gamma(T^\#) = \gamma(J_{\mathcal{H}}T^*J_{\mathcal{K}}) = \gamma(T^*) = \gamma(T),$$

because $J_{\mathcal{H}}$ (resp. $J_{\mathcal{K}}$) is a unitary operator on \mathcal{H} (resp. \mathcal{K}).

Remark 2.3. If \mathcal{M}_+ is a closed J -nonnegative subspace of a Krein space \mathcal{H} then

$$\gamma(G_{\mathcal{M}_+}) = \alpha^+, \tag{7}$$

where $\alpha^+ \in [0, 1]$ is the supremum among the constants $\alpha \in [0, 1]$ such that $\alpha\|f\|^2 \leq [f, f]$ for every $f \in \mathcal{M}_+$. From now on, the constant α^+ is called the *definiteness bound* of \mathcal{M}_+ . Notice that α^+ is in fact a maximum for the above set and \mathcal{M}_+ is uniformly J -positive if and only if $\alpha^+ > 0$.

Analogously, if \mathcal{M}_- is a J -nonpositive subspace then $\gamma(G_{\mathcal{M}_-}) = \alpha^-$, where α^- is the definiteness bound of \mathcal{M}_- , i.e.

$$\alpha^- = \max\{\alpha \in [0, 1] : [f, f] \leq -\alpha\|f\|^2 \text{ for every } f \in \mathcal{M}_-\}.$$

2.3 Frames for Hilbert spaces

The following is the standard notation and some basic results on frames for Hilbert spaces, see [6, 8, 16].

A *frame* for a Hilbert space \mathcal{H} is a family of vectors $\mathcal{F} = \{f_i\}_{i \in I} \subset \mathcal{H}$ for which there exist constants $0 < A \leq B < \infty$ such that

$$A \|f\|^2 \leq \sum_{i \in I} |\langle f, f_i \rangle|^2 \leq B \|f\|^2, \quad \text{for every } f \in \mathcal{H}. \quad (8)$$

The optimal constants (maximal for A and minimal for B) are known, respectively, as the upper and lower frame bounds.

If a family of vectors $\mathcal{F} = \{f_i\}_{i \in I}$ satisfies the upper bound condition in (8), then \mathcal{F} is a *Bessel family*. For a Bessel family $\mathcal{F} = \{f_i\}_{i \in I}$, the *synthesis operator* $T \in L(\ell_2(I), \mathcal{H})$ is defined by

$$Tx = \sum_{i \in I} \langle x, e_i \rangle f_i,$$

where $\{e_i\}_{i \in I}$ is the standard orthonormal basis of $\ell_2(I)$. It holds that \mathcal{F} is a frame for \mathcal{H} if and only if T is surjective. In this case, the operator $S = TT^* \in L(\mathcal{H})$ is invertible and is called the *frame operator*. It can be easily verified that

$$Sf = \sum_{i \in I} \langle f, f_i \rangle f_i, \quad \text{for every } f \in \mathcal{H}. \quad (9)$$

This implies that the frame bounds can be computed as: $A = \|S^{-1}\|^{-1}$ and $B = \|S\|$. From (9), it is also easy to obtain the *canonical reconstruction formula* for the vectors in \mathcal{H} :

$$f = \sum_{i \in I} \langle f, S^{-1}f_i \rangle f_i = \sum_{i \in I} \langle f, f_i \rangle S^{-1}f_i, \quad \text{for every } f \in \mathcal{H},$$

and the frame $\{S^{-1}f_i\}_{i \in I}$ is called the *canonical dual frame* of \mathcal{F} . More generally, if a frame $\mathcal{G} = \{g_i\}_{i \in I}$ satisfies

$$f = \sum_{i \in I} \langle f, g_i \rangle f_i = \sum_{i \in I} \langle f, f_i \rangle g_i, \quad \text{for every } f \in \mathcal{H}, \quad (10)$$

then \mathcal{G} is called a *dual frame* of \mathcal{F} .

3 J -frames: definition and basic properties

Let \mathcal{H} be a Krein space with fundamental symmetry J . Given a Bessel family $\mathcal{F} = \{f_i\}_{i \in I}$ in \mathcal{H} consider the synthesis operator $T \in L(\ell_2(I), \mathcal{H})$. If $I_+ = \{i \in I : [f_i, f_i] \geq 0\}$ and $I_- = \{i \in I : [f_i, f_i] < 0\}$, consider the orthogonal decomposition of $\ell_2(I)$ given by

$$\ell_2(I) = \ell_2(I_+) \oplus \ell_2(I_-), \quad (11)$$

and denote by P_{\pm} the orthogonal projection onto $\ell_2(I_{\pm})$. Also, let $T_{\pm} = TP_{\pm}$. If $\mathcal{M}_{\pm} = \overline{\text{span}\{f_i : i \in I_{\pm}\}}$, notice that $\text{span}\{f_i : i \in I_{\pm}\} \subseteq R(T_{\pm}) \subseteq \mathcal{M}_{\pm}$ and

$$R(T) = R(T_+) + R(T_-).$$

Definition. The Bessel family $\mathcal{F} = \{f_i\}_{i \in I}$ is a *J -frame* for \mathcal{H} if $R(T_+)$ is a maximal uniformly J -positive subspace of \mathcal{H} and $R(T_-)$ is a maximal uniformly J -negative subspace of \mathcal{H} .

Notice that, in particular, every J -orthogonalized basis of a Krein space \mathcal{H} is a J -frame for \mathcal{H} , because it generates a maximal dual pair, see [18, Ch. 1, §10.12].

If \mathcal{F} is a J -frame, as a consequence of its maximality, $R(T_{\pm})$ is closed. So, $R(T_{\pm}) = \mathcal{M}_{\pm}$ and, by [2, Corollary 1.5.2], $\mathcal{M}_+ + \mathcal{M}_- = \mathcal{H}$. Then, it follows that \mathcal{F} is a frame for the associated Hilbert space $(\mathcal{H}, \langle \cdot, \cdot \rangle)$ because

$$R(T) = R(T_+) + R(T_-) = \mathcal{M}_+ + \mathcal{M}_- = \mathcal{H}.$$

Given a Bessel family $\mathcal{F} = \{f_i\}_{i \in I}$, consider the subspaces $R(T_+)$ and $R(T_-)$ as above. If $K_{\pm} : \mathcal{D}_{\pm} \rightarrow \mathcal{H}_{\mp}$ is the angular operator associated to $R(T_{\pm})$, the *operator of transition* associated to the Bessel family \mathcal{F} is defined by

$$F = K_+P + K_-(I - P) : \mathcal{D}_+ + \mathcal{D}_- \rightarrow \mathcal{H},$$

where $P = \frac{1}{2}(I + J)$ is the J -selfadjoint projection onto \mathcal{H}_+ and \mathcal{D}_{\pm} is a subspace of \mathcal{H}_{\pm} (the domain of K_{\pm}), see [15].

Proposition 3.1. *Let $\mathcal{F} = \{f_i\}_{i \in I}$ be a Bessel family in \mathcal{H} . Then, \mathcal{F} is a J -frame if and only if F is everywhere defined (i.e. $\mathcal{D}_+ + \mathcal{D}_- = \mathcal{H}$) and $\|F\| < 1$.*

Proof. Proof See [15, Proposition 2.6].

It follows from the definition that, given a J -frame $\mathcal{F} = \{f_i\}_{i \in I}$ for the Krein space \mathcal{H} , $[f_i, f_i] \neq 0$ for every $i \in I$, i.e. $I_{\pm} = \{i \in I : \pm[f_i, f_i] > 0\}$. This fact allows to endow the coefficients space $\ell_2(I)$ with a Krein space structure. Denote $\sigma_i = \text{sgn}([f_i, f_i]) = \pm 1$ for every $i \in I$. Then, the diagonal operator $J_2 \in L(\ell_2(I))$ defined by

$$J_2 e_i = \sigma_i e_i, \quad \text{for every } i \in I, \quad (12)$$

is a selfadjoint involution on $\ell_2(I)$. Therefore, $\ell_2(I)$ with the fundamental symmetry J_2 is a Krein space.

Now, if $T \in L(\ell_2(I), \mathcal{H})$ is the synthesis operator of \mathcal{F} , the J -adjoints of T , T_+ and T_- can be easily calculated, in fact if $f \in \mathcal{H}$:

$$T_{\pm}^{\#} f = \pm \sum_{i \in I_{\pm}} [f, f_i] e_i,$$

$$\text{and } T^{\#} f = (T_+ + T_-)^{\#} f = T_+^{\#} f + T_-^{\#} f = \sum_{i \in I_+} [f, f_i] e_i - \sum_{i \in I_-} [f, f_i] e_i = \sum_{i \in I} \sigma_i [f, f_i] e_i.$$

Example 1. It is easy to see that not every frame of J -nonneutral vectors is a J -frame: given the Krein space obtained by endowing \mathbb{C}^3 with the sesquilinear form

$$[(x_1, x_2, x_3), (y_1, y_2, y_3)] = x_1 \overline{y_1} + x_2 \overline{y_2} - x_3 \overline{y_3},$$

consider $f_1 = (1, 0, \frac{1}{\sqrt{2}})$, $f_2 = (0, 1, \frac{1}{\sqrt{2}})$ and $f_3 = (0, 0, 1)$. Observe that $\mathcal{F} = \{f_1, f_2, f_3\}$ is a frame for \mathbb{C}^3 because it is a (linear) basis for the space.

On the other hand, $\mathcal{M}_+ = \text{span}\{f_1, f_2\}$ and $\mathcal{M}_- = \text{span}\{f_3\}$. If $(a, b, \frac{1}{\sqrt{2}}(a + b))$ is an arbitrary vector in \mathcal{M}_+ then

$$[f, f] = |a|^2 + |b|^2 - \frac{1}{2}|a + b|^2 = \frac{1}{2}|a - b|^2 \geq 0,$$

so \mathcal{M}_+ is a J -nonnegative subspace of \mathbb{C}^3 . But \mathcal{M}_+ is not uniformly J -positive, because $(1, 1, \sqrt{2}) \in \mathcal{M}_+$ is a (non trivial) J -neutral vector. Therefore, \mathcal{F} is not a J -frame for $(\mathbb{C}^3, [\cdot, \cdot])$.

The following is a handy way to construct J -frames for a given Krein space. Along this section, it will be shown that every J -frame can be realized in this way.

Example 2. Given a Krein space \mathcal{H} with fundamental symmetry J , let \mathcal{M}_+ (resp. \mathcal{M}_-) be a maximal uniformly J -positive (resp. J -negative) subspace of \mathcal{H} . If $\mathcal{F}_{\pm} = \{f_i\}_{i \in I_{\pm}}$ is a frame for the Hilbert space $(\mathcal{M}_{\pm}, \pm[\cdot, \cdot])$ then $\mathcal{F} = \mathcal{F}_+ \cup \mathcal{F}_-$ is a J -frame for \mathcal{H} .

Indeed, by Remark 2.1, \mathcal{F}_+ and \mathcal{F}_- are Bessel families in \mathcal{H} . Hence, \mathcal{F} is a Bessel family and, if $I = I_+ \dot{\cup} I_-$ (the disjoint union of I_+ and I_-), the synthesis operator $T \in L(\ell_2(I), \mathcal{H})$ of \mathcal{F} is given by

$$Tx = T_+x_+ + T_-x_- \quad \text{if } x = x_+ + x_- \in \ell_2(I_+) \oplus \ell_2(I_-) =: \ell_2(I),$$

where $T_{\pm} : \ell_2(I_{\pm}) \rightarrow \mathcal{M}_{\pm}$ is the synthesis operator of \mathcal{F}_{\pm} . Then, it is clear that $R(TP_{\pm}) = \mathcal{M}_{\pm}$ is a maximal uniformly J -definite subspace of \mathcal{H} .

Proposition 3.2. Let $\mathcal{F} = \{f_i\}_{i \in I}$ be a J -frame for \mathcal{H} . Then, $\mathcal{F}_\pm = \{f_i\}_{i \in I_\pm}$ is a frame for the Hilbert space $(\mathcal{M}_\pm, \pm[\cdot, \cdot])$, i.e. there exist constants $B_- \leq A_- < 0 < A_+ \leq B_+$ such that

$$A_\pm[f, f] \leq \sum_{i \in I_\pm} |[f, f_i]|^2 \leq B_\pm[f, f] \quad \text{for every } f \in \mathcal{M}_\pm. \quad (13)$$

Proof. Proof If $\mathcal{F} = \{f_i\}_{i \in I}$ is a J -frame for \mathcal{H} , then $R(T_+) = \mathcal{M}_+$ is a (maximal) uniformly J -positive subspace of \mathcal{H} . So, T_+ is a surjection from $\ell_2(I)$ onto the Hilbert space $(\mathcal{M}_+, [\cdot, \cdot])$. Therefore, \mathcal{F}_+ is a frame for $(\mathcal{M}_+, [\cdot, \cdot])$. In particular, there exist constants $0 < A_+ \leq B_+$ such that Eq. (13) is satisfied for \mathcal{M}_+ . The assertion on \mathcal{F}_- follows analogously.

Now, assuming that \mathcal{F} is a J -frame for a Krein space $(\mathcal{H}, [\cdot, \cdot])$, a set of constants $\{B_-, A_-, A_+, B_+\}$ satisfying Eq. (13) is going to be computed. They depend only on the definiteness bounds for $R(T_\pm)$, the norm and the reduced minimum modulus of T_\pm .

Suppose that \mathcal{F} is a J -frame for a Krein space $(\mathcal{H}, [\cdot, \cdot])$ with synthesis operator $T \in L(\ell_2(I), \mathcal{H})$. Since $R(T_+) = \mathcal{M}_+$ is a (maximal) uniformly J -positive subspace of \mathcal{H} , there exists $\alpha_+ > 0$ such that $\alpha_+ \|f\|^2 \leq [f, f]$ for every $f \in \mathcal{M}_+$. So,

$$\sum_{i \in I_+} |[f, f_i]|^2 = \|T_+^\# f\|^2 \leq \|T_+^\#\|^2 \|f\|^2 \leq B_+[f, f], \quad \text{for every } f \in \mathcal{M}_+,$$

where $B_+ = \frac{\|T_+^\#\|^2}{\alpha_+} = \frac{\|T_+\|^2}{\alpha_+}$. Furthermore, since $N(T_+^\#)^\perp = J(\mathcal{M}_+)$, if $f \in \mathcal{M}_+$,

$$\begin{aligned} \sum_{i \in I_+} |[f, f_i]|^2 &= \|T_+^\# f\|^2 = \|T_+^\# P_{J(\mathcal{M}_+)} f\|^2 \geq \gamma(T_+^\#)^2 \|P_{J(\mathcal{M}_+)} f\|^2 = \gamma(T_+)^2 \|P_{\mathcal{M}_+} Jf\|^2 = \\ &= \gamma(T_+)^2 \|G_{\mathcal{M}_+} f\|^2 \geq \gamma(T_+)^2 \gamma(G_{\mathcal{M}_+})^2 \|f\|^2 \geq A_+[f, f], \end{aligned}$$

where $A_+ = \gamma(T_+)^2 \gamma(G_{\mathcal{M}_+})^2 = \gamma(T_+)^2 \alpha_+^2$, see Remark 2.3.

Analogously, $A_- = -\gamma(T_-)^2 \alpha_-^2$ and $B_- = -\frac{\|T_-\|^2}{\alpha_-}$ satisfy Eq (13) for every $f \in R(T_-) = \mathcal{M}_-$, if α_- is the definiteness bound of the (maximal) uniformly J -negative subspace \mathcal{M}_- .

Usually, the bounds $A_\pm = \pm \alpha_\pm^2 \gamma(T_\pm)^2$ and $B_\pm = \pm \frac{\|T_\pm\|^2}{\alpha_\pm}$ are not optimal for the J -frame \mathcal{F} .

Definition. Let \mathcal{F} be a J -frame for the Krein space \mathcal{H} . The optimal constants $B_- \leq A_- < 0 < A_+ \leq B_+$ satisfying Eq. (13) are called the J -frame bounds of \mathcal{F} .

In order to compute the J -frame bounds associated to a J -frame $\mathcal{F} = \{f_i\}_{i \in I}$, consider the uniformly J -definite subspaces \mathcal{M}_+ and \mathcal{M}_- . Recall that $\mathcal{F}_+ = \{f_i\}_{i \in I_+}$ is a frame for the Hilbert space $(\mathcal{M}_+, [\cdot, \cdot])$. Then, if $G_+ = G_{\mathcal{M}_+}|_{\mathcal{M}_+} \in GL(\mathcal{M}_+)$, the frame bounds for \mathcal{F}_+ are given by $A_+ = \|(S_{G_+})^{-1}\|_+^{-1}$ and $B_+ = \|S_{G_+}\|_+$, where $S_{G_+} = T_+ T_+^* G_+$ is the frame operator of \mathcal{F}_+ and $\|f\|_+ = [f, f]^{1/2} = \|G_+^{1/2} f\|$, $f \in \mathcal{M}_+$, is the operator norm associated to the inner product $[\cdot, \cdot]$. Therefore,

$$A_+ = \|(S_{G_+})^{-1}\|_+^{-1} = \|G_+^{1/2} (T_+ T_+^* G_+)^{-1}\|^{-1} = \|G_+^{-1/2} (T_+ T_+^*)^{-1}\|^{-1},$$

and $B_+ = \|S_{G_+}\|_+ = \|G_+^{1/2} T_+ T_+^* G_+\|$. Analogously, it follows that $\mathcal{F}_- = \{f_i\}_{i \in I_-}$ is a frame for the Hilbert space $(\mathcal{M}_-, -[\cdot, \cdot])$. So, the frame bounds for \mathcal{F}_- are given by

$$A_- = \|G_-^{-1/2} (T_- T_-^*)^{-1}\|^{-1} \quad \text{and} \quad B_- = \|G_-^{1/2} T_- T_-^* G_-\|,$$

where $G_- = G_{\mathcal{M}_-}|_{\mathcal{M}_-} \in GL(\mathcal{M}_-)$. Thus, the J -frame bound associated to \mathcal{F} can be fully characterized in terms of T_\pm and the Gramian operators $G_{\mathcal{M}_\pm}$.

3.1 Characterizing J -frames in terms of frame inequalities

Given a Bessel family $\mathcal{F} = \{f_i\}_{i \in I}$ in a Krein space \mathcal{H} , the inequalities:

$$A[f, f] \leq \sum_{i \in I} |[f, f_i]|^2 \leq B[f, f] \quad \text{for every } f \in \mathcal{M} = \overline{\text{span}\{f_i : i \in I\}}, \quad (14)$$

with $B \geq A > 0$, ensure that \mathcal{M} is a J -nonnegative subspace of \mathcal{H} . However, they do not imply that \mathcal{M} is uniformly J -positive, i.e. $(\mathcal{M}, [\cdot, \cdot])$ is not necessarily an inner product space. See the example below.

Example 3. Consider again the Krein space $(\mathbb{C}^3, [\cdot, \cdot])$ as in Example 1. As it was mentioned before, $\mathcal{M} = \text{span}\{f_1 = (1, 0, 1/\sqrt{2}), f_2 = (0, 1, 1/\sqrt{2})\}$ is a J -nonnegative but not uniformly J -positive subspace of \mathbb{C}^3 .

In this case, the orthogonal basis

$$v_1 = (\frac{1}{2}, \frac{1}{2}, \frac{1}{\sqrt{2}}), v_2 = (\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}, 0) \text{ and } v_3 = (\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, -1),$$

is a basis of eigenvectors of $G_{\mathcal{M}}$, corresponding to the eigenvalues $\lambda_1 = 0, \lambda_2 = 1$ and $\lambda_3 = 0$, respectively. Moreover, $\mathcal{M} = \text{span}\{v_1, v_2\}$. Thus, if $f \in \mathcal{M}$ there exists $\alpha, \beta \in \mathbb{C}$ such that $f = \alpha v_1 + \beta v_2$ and then, since $G_{\mathcal{M}}v_1 = 0 \in \mathbb{C}^3$, it is easy to see that

$$|[f, f_1]|^2 + |[f, f_2]|^2 = |\beta|^2(|\langle v_2, f_1 \rangle|^2 + |\langle v_2, f_2 \rangle|^2) = |\beta|^2 = [f, f].$$

Therefore, Eq. (14) holds with $A = B = 1$, but $\{f_1, f_2\}$ cannot be extended to a J -frame, since \mathcal{M} is not a uniformly J -positive subspace.

The next result gives a complete characterization of the families satisfying Eq. (14) for $B \geq A > 0$. It is straightforward to formulate and prove analogues of all these assertions for a family satisfying Eq. (14) for negative constants $B \leq A < 0$.

Proposition 3.3. *Given a Bessel family $\mathcal{F} = \{f_i\}_{i \in I}$ in a Krein space \mathcal{H} , let $\mathcal{M} = \overline{\text{span}\{f_i : i \in I\}}$ and $\mathcal{N} = \mathcal{M} \cap \mathcal{M}^{\perp}$. If there exist constants $0 < A \leq B$ such that*

$$A[f, f] \leq \sum_{i \in I} |[f, f_i]|^2 \leq B[f, f] \quad \text{for every } f \in \mathcal{M}, \quad (15)$$

then $\mathcal{M} \ominus \mathcal{N}$ is a (closed) uniformly J -positive subspace of \mathcal{M} . Moreover, if \mathcal{F} is a frame for the Hilbert space $(\mathcal{M}, \langle \cdot, \cdot \rangle)$, the converse holds.

Proof. Proof First, suppose that there exist $0 < A \leq B$ such that Eq. (15) holds. So, \mathcal{M} is a J -nonnegative subspace of \mathcal{H} , or equivalently, $(\mathcal{M}, [\cdot, \cdot])$ is a semi-inner product space.

If $T \in L(\ell_2(I), \mathcal{H})$ is the synthesis operator of the Bessel sequence \mathcal{F} and $C = \|T^*\|^2 > 0$, then $TT^* \leq CP_{\mathcal{M}}$. So, using Eq. (15) it is easy to see that:

$$A\langle G_{\mathcal{M}}f, f \rangle \leq \|T^{\#}(P_{\mathcal{M}}f)\|^2 = \langle (P_{\mathcal{M}}JTT^*JP_{\mathcal{M}})f, f \rangle \leq C\langle (G_{\mathcal{M}})^2f, f \rangle, \quad f \in \mathcal{H}. \quad (16)$$

Thus, $0 \leq G_{\mathcal{M}} \leq \frac{C}{A}(G_{\mathcal{M}})^2$. Applying Douglas' theorem [11] it is easy to see that

$$R((G_{\mathcal{M}})^{1/2}) \subseteq R(G_{\mathcal{M}}) \subseteq R((G_{\mathcal{M}})^{1/2}).$$

Moreover, it follows that $R(G_{\mathcal{M}})$ is closed because $R(G_{\mathcal{M}}) = R((G_{\mathcal{M}})^{1/2})$.

Let $\mathcal{M}' = \mathcal{M} \ominus \mathcal{N}$ and notice that \mathcal{M}' is a closed uniformly J -positive subspace of \mathcal{H} . In fact, since $R(G_{\mathcal{M}})$ is closed, there exists $\alpha > 0$ such that

$$[f, f] = \langle G_{\mathcal{M}}f, f \rangle = \|(G_{\mathcal{M}})^{1/2}f\|^2 \geq \alpha\|f\|^2 \quad \text{for every } f \in N(G_{\mathcal{M}})^{\perp} = \mathcal{M} \ominus \mathcal{N}.$$

Conversely, suppose that \mathcal{F} is a frame for $(\mathcal{M}, \langle \cdot, \cdot \rangle)$, i.e. there exist constants $B' \geq A' > 0$ such that

$$A'P_{\mathcal{M}} \leq TT^* \leq B'P_{\mathcal{M}},$$

where $T \in L(\ell_2(I), \mathcal{M})$ is the synthesis operator of \mathcal{F} . If $\mathcal{M}' = \mathcal{M} \ominus \mathcal{N}$ is a uniformly J -positive subspace of \mathcal{H} , then there exists $\alpha > 0$ such that $\alpha P_{\mathcal{M}'} \leq G_{\mathcal{M}'} \leq P_{\mathcal{M}'}$. As a consequence of Douglas' theorem, $R((G_{\mathcal{M}'})^{1/2}) = \mathcal{M}' = R(G_{\mathcal{M}'})$. Since $G_{\mathcal{M}} = G_{\mathcal{M}'}$ it is easy to see that

$$A'(G_{\mathcal{M}})^2 = A'(G_{\mathcal{M}'})^2 \leq P_{\mathcal{M}}JTT^*JP_{\mathcal{M}} \leq B'(G_{\mathcal{M}'})^2 = B'(G_{\mathcal{M}})^2.$$

Therefore, $R(P_{\mathcal{M}}JT) = R(G_{\mathcal{M}'}) = R((G_{\mathcal{M}'}^{1/2})^2)$, or equivalently, there exist $B \geq A > 0$ such that

$$AG_{\mathcal{M}} = AG_{\mathcal{M}'} \leq P_{\mathcal{M}}JTT^*JP_{\mathcal{M}} \leq BG_{\mathcal{M}'} = BG_{\mathcal{M}},$$

i.e. $A[f, f] \leq \sum_{i \in I} |[f, f_i]|^2 \leq B[f, f]$ for every $f \in \mathcal{M}$.

Theorem 3.4. *Let $\mathcal{F} = \{f_i\}_{i \in I}$ be a frame for \mathcal{H} . If $I_{\pm} = \{i \in I : \pm[f_i, f_i] \geq 0\}$ and $\mathcal{M}_{\pm} = \overline{\text{span}\{f_i : i \in I_{\pm}\}}$ then, \mathcal{F} is a J -frame if and only if $\mathcal{M}_{\pm} \cap \mathcal{M}_{\pm}^{[\perp]} = \{0\}$ and there exist constants $B_{-} \leq A_{-} < 0 < A_{+} \leq B_{+}$ such that*

$$A_{\pm} [f, f] \leq \sum_{i \in I_{\pm}} |[f, f_i]|^2 \leq B_{\pm} [f, f] \quad \text{for every } f \in \mathcal{M}_{\pm}. \quad (17)$$

Proof. Proof If \mathcal{F} is a J -frame, the conditions on \mathcal{M}_{\pm} follow by its definition and by Proposition 3.2. Conversely, if \mathcal{M}_{+} is J -non degenerated and there exist constants $0 < A_{+} \leq B_{+}$ such that

$$A_{+} [f, f] \leq \sum_{i \in I_{+}} |[f, f_i]|^2 \leq B_{+} [f, f] \quad \text{for every } f \in \mathcal{M}_{+},$$

then, by Proposition 3.3, \mathcal{M}_{+} is a uniformly J -positive subspace of \mathcal{H} . Therefore, there exist constants $0 < A \leq B$ such that

$$A \|P_{\mathcal{M}_{+}} f\|^2 \leq \|T_{+}^{\#} P_{\mathcal{M}_{+}} f\|^2 \leq B \|P_{\mathcal{M}_{+}} f\|^2 \quad \text{for every } f \in \mathcal{H}.$$

But these inequalities can be rewritten as

$$A P_{\mathcal{M}_{+}} \leq P_{\mathcal{M}_{+}} J T_{+} T_{+}^{*} J P_{\mathcal{M}_{+}} \leq B P_{\mathcal{M}_{+}}.$$

Then, by Douglas' theorem, $R(P_{\mathcal{M}_{+}} J T_{+}) = R(P_{\mathcal{M}_{+}}) = \mathcal{M}_{+}$. Furthermore, $P_{J(\mathcal{M}_{+})}(R(T_{+})) = J(\mathcal{M}_{+})$ because

$$J(\mathcal{M}_{+}) = J(R(P_{\mathcal{M}_{+}} J T_{+})) = R((J P_{\mathcal{M}_{+}} J) T_{+}) = R(P_{J(\mathcal{M}_{+})} T_{+}) = P_{J(\mathcal{M}_{+})}(R(T_{+})).$$

Therefore, taking the counterimage of $P_{J(\mathcal{M}_{+})}(R(T_{+}))$ by $P_{J(\mathcal{M}_{+})}$, it follows that

$$\mathcal{H} = R(T_{+}) \dot{+} J(\mathcal{M}_{+})^{\perp} \subseteq \mathcal{M}_{+} \dot{+} \mathcal{M}_{+}^{[\perp]} = \mathcal{H}.$$

Thus, $R(T_{+}) = \mathcal{M}_{+}$ and \mathcal{F}_{+} is a frame for \mathcal{M}_{+} . Analogously, $\mathcal{F}_{-} = \{f_i\}_{i \in I_{-}}$ is a frame for \mathcal{M}_{-} . Finally, since \mathcal{F} is a frame for \mathcal{H} ,

$$\mathcal{H} = R(T) = R(T_{+}) + R(T_{-}),$$

which proves the maximality of $R(T_{\pm})$. Thus, \mathcal{F} is a J -frame for \mathcal{H} .

3.2 A geometrical characterization of J -frames

Let $\mathcal{F} = \{f_i\}_{i \in I}$ be a J -frame for \mathcal{H} and consider $\mathcal{F} = \mathcal{F}_{+} \cup \mathcal{F}_{-}$ the partition of \mathcal{F} into J -positive and J -negative vectors. Moreover, let \mathcal{M}_{\pm} be the (maximal) uniformly J -definite subspace of \mathcal{H} generated by \mathcal{F}_{\pm} .

The aim of this section is to show that it is possible to bound the correlation between vectors in \mathcal{F}_{+} (resp. \mathcal{F}_{-}) and vectors in the cone of neutral vectors $\mathcal{C} = \{n \in \mathcal{H} : [n, n] = 0\}$, in a strong sense:

$$|\langle f, n \rangle| \leq c_{\pm} \|f\| \|n\|, \quad f \in \mathcal{M}_{\pm}, \quad n \in \mathcal{C}, \quad (18)$$

for some constants $\frac{\sqrt{2}}{2} \leq c_{\pm} < 1$. In order to make these ideas precise, consider the notion of minimal angle between a subspace \mathcal{M} and the cone \mathcal{C} .

Definition. Given a closed subspace \mathcal{M} of the Krein space \mathcal{H} , consider

$$c_0(\mathcal{M}, \mathcal{C}) = \sup \{ |\langle m, n \rangle| : m \in \mathcal{M}, n \in \mathcal{C}, \|n\| = \|m\| = 1 \}, \quad (19)$$

Then, there exists a unique $\theta(\mathcal{M}, \mathcal{C}) \in [0, \frac{\pi}{4}]$ such that $\cos(\theta(\mathcal{M}, \mathcal{C})) = c_0(\mathcal{M}, \mathcal{C})$. In this case, $\theta(\mathcal{M}, \mathcal{C})$ is the *minimal angle* between \mathcal{M} and \mathcal{C} .

Observe that if the subspace \mathcal{M} contains a non trivial J -neutral vector (e.g. if \mathcal{M} is J -indefinite or J -semidefinite) then $c_0(\mathcal{M}, \mathcal{C}) = 1$, or equivalently, $\theta(\mathcal{M}, \mathcal{C}) = 0$. On the other hand, it will be shown that the minimal angle between a uniformly J -positive (resp. uniformly J -negative) subspace \mathcal{M} and \mathcal{C} is always bounded away from 0.

Proposition 3.5. *Let \mathcal{M} be a J -semidefinite subspace of \mathcal{H} with definiteness bound α . Then,*

$$c_0(\mathcal{M}, \mathcal{C}) = \frac{1}{\sqrt{2}} \left(\sqrt{\frac{1+\alpha}{2}} + \sqrt{\frac{1-\alpha}{2}} \right). \quad (20)$$

In particular, \mathcal{M} is uniformly J -definite if and only if $c_0(\mathcal{M}, \mathcal{C}) < 1$.

Proof. Proof Let $\mathcal{H} = \mathcal{H}_+ \oplus \mathcal{H}_-$ be a fundamental decomposition of \mathcal{H} and suppose that \mathcal{M} is a J -nonnegative subspace of \mathcal{H} .

Let $m \in \mathcal{M}$ with $\|m\| = 1$. Then, there exist (unique) $m^\pm \in \mathcal{H}_\pm$ such that $m = m^+ + m^-$. In this case,

$$1 = \|m\|^2 = \|m^+\|^2 + \|m^-\|^2 \quad \text{and} \quad \alpha \leq [m, m] = \|m^+\|^2 - \|m^-\|^2. \quad (21)$$

Claim: Fixed $m \in \mathcal{M}$ with $\|m\| = 1$, $\sup \{ |\langle m, n \rangle| : n \in \mathcal{C}, \|n\| = 1 \} = \frac{1}{\sqrt{2}} (\|m^+\| + \|m^-\|)$.

Indeed, consider $n \in \mathcal{C}$ with $\|n\| = 1$. Then, there exist (unique) $n_\pm \in \mathcal{H}_\pm$ such that $n = n^+ + n^-$. In this case,

$$0 = [n, n] = \|n^+\|^2 - \|n^-\|^2 \quad \text{and} \quad 1 = \|n\|^2 = \|n^+\|^2 + \|n^-\|^2,$$

which imply that $\|n^+\| = \|n^-\| = \frac{1}{\sqrt{2}}$. Therefore,

$$|\langle m, n \rangle| \leq |\langle m^+, n^+ \rangle| + |\langle m^-, n^- \rangle| \leq \frac{1}{\sqrt{2}} (\|m^+\| + \|m^-\|).$$

On the other hand, if $m^- \neq 0$ then let $n_m := \frac{1}{\sqrt{2}} (\frac{m^+}{\|m^+\|} + \frac{m^-}{\|m^-\|})$, otherwise consider $n_m = \frac{1}{\sqrt{2}} (m + z)$, with $z \in \mathcal{H}_-$, $\|z\| = 1$. Now, it is easy to see that $n_m \in \mathcal{C}$ and that $|\langle m, n_m \rangle| = \frac{1}{\sqrt{2}} (\|m^+\| + \|m^-\|)$ which together with the previous facts prove the claim.

Now, let $\mathcal{M}_1 = \{m = m^+ + m^- \in \mathcal{M} : m^\pm \in \mathcal{H}_\pm, \|m\| = 1\}$. Using the claim above it follows that

$$c_0(\mathcal{M}, \mathcal{C}) = \frac{1}{\sqrt{2}} \sup_{m \in \mathcal{M}_1} (\|m^+\| + \|m^-\|). \quad (22)$$

If $\alpha = 1$ then \mathcal{M} is a subspace of \mathcal{H}_+ . Also, it is easy to see that $c_0(\mathcal{M}, \mathcal{C}) = \frac{1}{\sqrt{2}}$. Thus, in this particular case, $c_0(\mathcal{M}, \mathcal{C}) = \frac{1}{\sqrt{2}} \left(\sqrt{\frac{1+\alpha}{2}} + \sqrt{\frac{1-\alpha}{2}} \right)$.

On the other hand, if $\alpha < 1$, let $k_0 \in \mathbb{N}$ be such that $\frac{1-\alpha}{2} > \frac{1}{2k_0}$. Observe that, by the definition of the definiteness bound, for every integer $k \geq k_0$ there exists $m_k = m_k^+ + m_k^- \in \mathcal{M}_1$ such that $\alpha \leq \|m_k^+\|^2 - \|m_k^-\|^2 < \alpha + \frac{1}{k}$. Then, it follows that

$$\alpha + 1 \leq 2\|m_k^+\|^2 < \alpha + 1 + \frac{1}{k},$$

or equivalently, $\sqrt{\frac{\alpha+1}{2}} \leq \|m_k^+\| < \sqrt{\frac{\alpha+1}{2} + \frac{1}{2k}}$. Moreover, $\|m_k^-\| = \sqrt{1 - \|m_k^+\|^2}$ implies that

$$\sqrt{\frac{1-\alpha}{2} - \frac{1}{2k}} < \|m_k^-\| \leq \sqrt{\frac{1-\alpha}{2}}.$$

Therefore, for every integer $k \geq k_0$ there exists $m_k \in \mathcal{M}_1$ such that

$$\sqrt{\frac{1-\alpha}{2} - \frac{1}{2k}} + \sqrt{\frac{\alpha+1}{2}} < \|m_k^+\| + \|m_k^-\| < \sqrt{\frac{\alpha+1}{2} + \frac{1}{2k}} + \sqrt{\frac{1-\alpha}{2}}.$$

Thus, $c_0(\mathcal{M}, \mathcal{C}) = \frac{1}{\sqrt{2}} \left(\sqrt{\frac{1+\alpha}{2}} + \sqrt{\frac{1-\alpha}{2}} \right)$.

Assume now that \mathcal{M} is a J -nonpositive subspace of $(\mathcal{H}, [\cdot, \cdot])$ with definiteness bound α , for $0 \leq \alpha \leq 1$. Then, \mathcal{M} is a J -nonnegative subspace of the antispaces $(\mathcal{H}, -[\cdot, \cdot])$, with the same definiteness bound α . Furthermore, the cone of J -neutral vectors for the antispaces is the same as for the initial Krein space $(\mathcal{H}, [\cdot, \cdot])$. Therefore, we can apply the previous arguments and conclude that Eq.(20) also holds for J -nonpositive subspaces.

Finally, the last assertion in the statement follows from the formula in Eq. (20).

Let \mathcal{F} be a J -frame for \mathcal{H} as above. Notice that the Eq. (18) holds for some constant $\frac{\sqrt{2}}{2} \leq c_{\pm} < 1$ if and only if $c_0(\mathcal{M}_{\pm}, \mathcal{C}) < 1$, i.e. that the minimal angles $\theta(\mathcal{M}_{\pm}, \mathcal{C})$ are bounded away from 0. This is intimately related with the fact that the aperture between the subspaces \mathcal{M}_+ (resp. \mathcal{M}_-) and \mathcal{H}_+ (resp. \mathcal{H}_-) is bounded away from $\frac{\pi}{4}$, whenever $\mathcal{H} = \mathcal{H}_+ \oplus \mathcal{H}_-$ is a fundamental decomposition.

Remark 3.6. Given a Krein space \mathcal{H} , fix a fundamental decomposition $\mathcal{H} = \mathcal{H}_+ \oplus \mathcal{H}_-$. Then, if \mathcal{M} is a J -nonnegative subspace of \mathcal{H} the minimal angle between \mathcal{M} and \mathcal{C} is related with the *aperture* $\Phi(\mathcal{M}, \mathcal{H}_+)$ between the subspaces \mathcal{M} and \mathcal{H}_+ , see [1] and Exercises 3–6 to [18, Ch. 1, §8]. In fact, if $K \in L(\mathcal{H}_+, \mathcal{H}_-)$ is the angular operator associated to \mathcal{M} then, by [18, Ch. 1, §8 Exercise 4],

$$\Phi(\mathcal{M}, \mathcal{H}_+) = \frac{\|K\|}{\sqrt{1 + \|K\|^2}}.$$

Also, if α is the definiteness bound of \mathcal{M} then $\|K\| = \sqrt{\frac{1-\alpha}{1+\alpha}}$, see [18, Ch. 1, Lemma 8.4]. Therefore, $\Phi(\mathcal{M}, \mathcal{H}_+) = \frac{\|K\|}{\sqrt{1 + \|K\|^2}} = \sqrt{\frac{1-\alpha}{2}}$. Since $\Phi(\mathcal{M}, \mathcal{H}_+) = \sin \varphi(\mathcal{M}, \mathcal{H}_+)$ for an angle $\varphi(\mathcal{M}, \mathcal{H}_+) \in [0, \frac{\pi}{4}]$ between \mathcal{M} and \mathcal{H}_+ , it is easy to see that

$$\cos \varphi(\mathcal{M}, \mathcal{H}_+) = \sqrt{1 - \sin^2 \varphi(\mathcal{M}, \mathcal{H}_+)} = \sqrt{\frac{1+\alpha}{2}}.$$

Therefore, if $\varphi = \varphi(\mathcal{M}, \mathcal{H}_+)$,

$$\cos(\frac{\pi}{4} - \varphi) = \frac{\sqrt{2}}{2} (\cos \varphi + \sin \varphi) = \frac{1}{\sqrt{2}} \left(\sqrt{\frac{1+\alpha}{2}} + \sqrt{\frac{1-\alpha}{2}} \right) = c_0(\mathcal{M}, \mathcal{C}),$$

i.e. $\varphi(\mathcal{M}, \mathcal{H}_+) + \theta(\mathcal{M}, \mathcal{C}) = \frac{\pi}{4}$.

The following result shows that, given a frame $\mathcal{F} = \{f_i\}_{i \in I}$ for \mathcal{H} , the positivity of the angles $\theta(\mathcal{M}_{\pm}, \mathcal{C})$ characterize it as a J -frame for \mathcal{H} .

Proposition 3.7. *Let $\mathcal{F} = \{f_i\}_{i \in I}$ be a frame for a Krein space \mathcal{H} . Then, \mathcal{F} is a J -frame for \mathcal{H} if and only if there exists a partition $I = I_1 \cup I_2$ such that*

$$\theta(\mathcal{M}_j, \mathcal{C}) > 0 \quad \text{for } j = 1, 2, \tag{23}$$

where $\mathcal{M}_j = \overline{\text{span}\{f_i : i \in I_j\}}$.

Proof. Proof If we assume that \mathcal{F} is a J -frame then, consider I_{\pm} and \mathcal{M}_{\pm} as usual. Then $I = I_+ \cup I_-$ is a partition of I into disjoint sets and \mathcal{M}_{\pm} are uniformly J -definite subspaces associated to \mathcal{F} . Hence, by Proposition 3.5, we see that Eq. (23) holds in this case.

Conversely, assume that there exists a partition of I with the properties above. Notice that Proposition 3.5 implies that \mathcal{M}_j is a uniformly J -definite subspace of \mathcal{H} , for $j = 1, 2$. On the other hand, since \mathcal{F} is a frame, $\mathcal{H} \subseteq \mathcal{M}_1 + \mathcal{M}_2$. Therefore, \mathcal{M}_1 and \mathcal{M}_2 have different positivity and they are maximal uniformly J -definite subspaces. Suppose that \mathcal{M}_1 is uniformly J -positive and \mathcal{M}_2 is uniformly J -negative.

Then, consider the orthogonal projection $P_j \in L(\ell_2(I))$ onto the subspace $\ell_2(I_j)$, for $j = 1, 2$. If $\mathcal{F} = \{f_i\}_{i \in I}$ is a frame for \mathcal{H} , its synthesis operator $T \in L(\ell_2(I), \mathcal{H})$ is surjective. Therefore,

$$R(T_1) \dot{+} R(T_2) = R(T) = \mathcal{H},$$

where $T_j = TP_j$, for $j = 1, 2$. Then, it is easy to see that $R(T_j) = \mathcal{M}_j$ for $j = 1, 2$ and \mathcal{F} is a J -frame for \mathcal{H} .

Remark 3.8. Let $(\mathcal{H}, \langle \cdot, \cdot \rangle)$ be a separable Hilbert space that models a signal space in which is considered a linear (robust and stable) encoding-decoding scheme for certain measurements, i.e. consider a (redundant) frame $\mathcal{G} = \{g_i\}_{i \in K}$ for \mathcal{H} .

Assume that the measurements of $x \in \mathcal{H}$ are given by $y_1 = Px$ and $y_2 = (I - P)x$, where $P \in L(\mathcal{H})$ is an orthogonal projection (for instance, P and $I - P$ are low pass and high pass filters, respectively). Suppose that the signals having the same energy in $R(P)$ and $R(I - P) = N(P)$ (i.e. signals $x \in \mathcal{H}$ such that $\|y_1\|^2 = \|y_2\|^2$) are considered disturbances, see e.g. [5, 20].

Notice that, sampling the measurements y_1, y_2 with the frame \mathcal{G} is the same as sampling $y = (y_1, y_2) \in \mathcal{H} \times \mathcal{H}$ with the frame $\mathcal{F} = \{f_i\}_{i \in I} = \{(g_i, 0)\}_{i \in K} \cup \{(0, g_i)\}_{i \in K}$ for $\mathcal{H} \times \mathcal{H}$.

It is easy to see that, the space $\mathcal{K} = \mathcal{H} \times \mathcal{H}$ with the indefinite product $[y, z] = \langle y_1, z_1 \rangle - \langle y_2, z_2 \rangle$ is a Krein space, where $y = (y_1, y_2), z = (z_1, z_2) \in \mathcal{K}$ are the measurements of signals in \mathcal{H} . Observe that the set of disturbances is characterized as the set of J -neutral vectors \mathcal{C} of \mathcal{K} .

Also, notice that \mathcal{F} is a J -frame for \mathcal{K} . Hence, the (sampling) vectors of the frame \mathcal{F} are away from the disturbances set \mathcal{C} .

Now, consider any (redundant) J -frame $\mathcal{F} = \{f_i\}_{i \in I}$ for $(\mathcal{K}, [\cdot, \cdot])$. As usual, denote \mathcal{M}_+ and \mathcal{M}_- the maximal uniformly J -definite subspaces generated by \mathcal{F} . Since \mathcal{M}_\pm is uniformly J -definite, Proposition 3.5 shows that $c_0(\mathcal{M}_\pm, \mathcal{C}) < 1$, which is a bound for the correlation between the sampling vectors in \mathcal{F} and the disturbances of \mathcal{C} because

$$|\langle f_i, n \rangle| \leq c_0(\mathcal{M}_\pm, \mathcal{C}) \|f_i\| \|n\| \quad \text{whenever } i \in I_\pm \text{ and } n \in \mathcal{C}. \quad (24)$$

That is, J -frames provide a class of frames for \mathcal{K} with the desired properties. Moreover, later in Proposition 5.3, it will be shown that the J -frame \mathcal{F} admits a (canonical) dual J -frame that induces a linear (indefinite) stable and redundant encoding-decoding scheme in which the correlation between both the sampling and reconstructing vectors and the cone of neutral vectors is bounded from above. These remarks provide a quantitative measure of the advantage of considering J -frames with respect to usual frames in this setting.

4 On the synthesis operator of a J -frame

If \mathcal{F} is a J -frame with synthesis operator T , then $QT = T_+ = TP_+$, where $Q = P_{\mathcal{M}_+ // \mathcal{M}_-}$. Therefore,

$$Q = QTT^\dagger = TP_+T^\dagger.$$

So, given a surjective operator $T : \ell_2(I) \rightarrow \mathcal{H}$, the idempotency of TP_+T^\dagger is a necessary condition for T to be the synthesis operator of a J -frame.

Lemma 4.1. *Let $T \in L(\ell_2(I), \mathcal{H})$ be surjective. Suppose that P_S is the orthogonal projection onto a closed subspace \mathcal{S} of $\ell_2(I)$ such that $c(\mathcal{S}, N(T)^\perp) < 1$. Then, $TP_S T^\dagger$ is a projection if and only if*

$$N(T) = \mathcal{S} \cap N(T) \oplus \mathcal{S}^\perp \cap N(T).$$

Proof. Proof Suppose that $Q = TP_S T^\dagger$ is a projection. Then, if $P = P_{N(T)^\perp}$, $E = PP_S P$ is an orthogonal projection because it is selfadjoint and

$$E^2 = (PP_S P)^2 = PP_S PP_S P = T^\dagger (TP_S T^\dagger)^2 T = T^\dagger (TP_S T^\dagger) T = PP_S P = E.$$

Therefore, $(PP_S)^k = E^{k-1} P_S = EP_S = (PP_S)^2$ for every $k \geq 2$. So, by [10, Lemma 18],

$$PP_S = P_S \wedge P = P_S P.$$

Then, since P_S and P commute, it follows that $N(T) = \mathcal{S} \cap N(T) \oplus \mathcal{S}^\perp \cap N(T)$ (see [10, Lemma 9]).

Conversely, suppose that $N(T) = \mathcal{S} \cap N(T) \oplus \mathcal{S}^\perp \cap N(T)$. Then, P_S and P commute and

$$(TP_S T^\dagger)^2 = TP_S (T^\dagger T) P_S T^\dagger = TP_S PP_S T^\dagger = TPP_S T^\dagger = TP_S T^\dagger.$$

Hereafter consider the set of possible decompositions of \mathcal{H} as a (direct) sum of a pair of maximal uniformly definite subspaces, or equivalently, the associated set of projections:

$$\mathcal{Q} = \{Q \in L(\mathcal{H}) : Q^2 = Q, R(Q) \text{ is uniformly } J\text{-positive and } N(Q) \text{ is uniformly } J\text{-negative}\}.$$

Proposition 4.2. *Let $T \in L(\ell_2(I), \mathcal{H})$ be surjective. Then, T is the synthesis operator of a J -frame if and only if there exists $I_+ \subset I$ such that $\ell_2(I_+)$ (as a subspace of $\ell_2(I)$) satisfies $c(N(T)^\perp, \ell_2(I_+)) < 1$ and*

$$TP_+T^\dagger \in \mathcal{Q},$$

where $P_+ \in L(\ell_2(I))$ is the orthogonal projection onto $\ell_2(I_+)$.

Proof. Proof If T is the synthesis operator of a J -frame, the existence of such a subset I_+ has already been discussed before.

Conversely, suppose that there exists such a subset I_+ of I . Then, since $c(N(T)^\perp, \ell_2(I_+)) < 1$ and $Q = TP_+T^\dagger \in \mathcal{Q}$, it follows from Lemma 4.1 that P_+ and $P = P_{N(T)^\perp}$ commute. Therefore,

$$QT = TP_+P = TPP_+ = TP_+,$$

and $(I-Q)T = T(I-P_+)$. Hence, $R(TP_+) = R(Q)$ is (maximal) uniformly J -positive and $R(T(I-P_+)) = N(Q)$ is (maximal) uniformly J -negative. Therefore $\mathcal{F} = \{Te_i\}_{i \in I}$ is by definition a J -frame for \mathcal{H} .

Theorem 4.3. *Given a surjective operator $T \in L(\ell_2(I), \mathcal{H})$, the following conditions are equivalent:*

1. *There exists $U \in \mathcal{U}(\ell_2(I))$ such that TU is the synthesis operator of a J -frame.*
2. *There exists $Q \in \mathcal{Q}$ such that*

$$QTT^*(I-Q)^* = 0. \tag{25}$$

3. *There exist closed range operators $T_1, T_2 \in L(\ell_2(I), \mathcal{H})$ such that $T = T_1 + T_2$, $R(T_1)$ is uniformly J -positive, $R(T_2)$ is uniformly J -negative and $T_1T_2^* = T_2T_1^* = 0$.*

Proof. Proof 1. \Rightarrow 2.: Suppose that there exists $U \in \mathcal{U}(\ell_2(I))$ such that $V = TU$ is the synthesis operator of a J -frame. If $I_\pm = \{i \in I : \pm[Ve_i, Ve_i] > 0\}$ and $P_\pm \in L(\ell_2(I))$ is the orthogonal projection onto $\ell_2(I_\pm)$, define $V_\pm = VP_\pm$. Then, $V = V_+ + V_-$ and $\mathcal{M}_\pm = R(V_\pm)$ is a maximal uniformly J -definite subspace. So, considering $Q = P_{\mathcal{M}_+//\mathcal{M}_-} \in \mathcal{Q}$, it is easy to see that $QV = V_+$, $(I-Q)V = V_-$ and

$$QTT^*(I-Q)^* = QVV^*(I-Q)^* = V_+V_-^* = VP_+P_-V^* = 0.$$

2. \Rightarrow 3.: Suppose that there exists $Q \in \mathcal{Q}$ such that $QTT^*(I-Q)^* = 0$. Defining $T_1 = QT$ and $T_2 = (I-Q)T$, it follows that $T = T_1 + T_2$, $R(T_1) = R(Q)$ is uniformly J -positive, $R(T_2) = N(Q)$ is uniformly J -negative and

$$T_1T_2^* = T_2T_1^* = 0,$$

because Eq. (25) says that $R(T_2^*) = R(T^*(I-Q)^*) \subseteq N(QT) = N(T_1)$.

3. \Rightarrow 1.: If there exist closed range operators $T_1, T_2 \in L(\ell_2(I), \mathcal{H})$ satisfying the conditions of item 3., notice that $T_1T_2^* = 0$ implies that $N(T_2)^\perp \subseteq N(T_1)$, or equivalently, $N(T_1)^\perp \subseteq N(T_2)$.

Consider the projection $Q = P_{R(T_1)//R(T_2)} \in \mathcal{Q}$ and notice that $QT = T_1$ and $(I-Q)T = T_2$. If $\mathcal{B}_1 = \{u_i\}_{i \in I_1}$ is an orthonormal basis of $N(T_1)^\perp$, consider the family $\{f_i^+\}_{i \in I_1}$ in \mathcal{H} given by $f_i^+ = Tu_i$. But, if $i \in I_1$,

$$f_i^+ = QTu_i + (I-Q)Tu_i = T_1u_i \in R(T_1),$$

because $u_i \in N(T_1)^\perp \subseteq N(T_2)$. Therefore, $\{f_i^+\}_{i \in I_1} \subseteq R(T_1)$. Since T_1 is an isomorphism between $N(T_1)^\perp$ and $R(T_1)$, it follows that $R(T_1) = \overline{\text{span}\{f_i^+\}_{i \in I_1}}$.

Analogously, if $\mathcal{B}_2 = \{b_i\}_{i \in I_2}$ is an orthonormal basis of $N(T_1)$, the family $\{f_i^-\}_{i \in I_2}$ defined by $f_i^- = Tb_i$ ($i \in I_2$) lies in $R(T_2)$. Since T_2 is an isomorphism between $N(T_2)^\perp$ and $R(T_2)$, it follows that

$$R(T_2) = T_2(N(T_1)) \subseteq \overline{\text{span}\{f_i^-\}_{i \in I_2}} \subseteq R(T_2).$$

Finally, consider $U \in \mathcal{U}(\ell_2(I))$ which turns the standard orthonormal basis $\{e_i\}_{i \in I}$ into $\mathcal{B}_1 \cup \mathcal{B}_2$. Then, if $V = TU$ and $\mathcal{F} = \{Ve_i\}_{i \in I} = \{f_i^+\}_{i \in I_1} \cup \{f_i^-\}_{i \in I_2}$, it is easy to see that

$$I_+ = \{i \in I : [Ve_i, Ve_i] > 0\} = I_1 \quad \text{and} \quad I_- = \{i \in I : [Ve_i, Ve_i] < 0\} = I_2.$$

So, $R(V_+) = R(T_1)$ is maximal uniformly J -positive and $R(V_-) = R(T_2)$ is maximal uniformly J -negative. Therefore, \mathcal{F} is a J -frame for \mathcal{H} with synthesis operator $V = TU$.

5 The J -frame operator

Definition. Given a J -frame $\mathcal{F} = \{f_i\}_{i \in I}$, the J -frame operator $S : \mathcal{H} \rightarrow \mathcal{H}$ is defined by

$$Sf = \sum_{i \in I} \sigma_i [f, f_i] f_i, \quad \text{for every } f \in \mathcal{H},$$

where $\sigma_i = \text{sgn}([f_i, f_i])$.

The following proposition compiles some basic properties of the J -frame operator.

Proposition 5.1. *Let $\mathcal{F} = \{f_i\}_{i \in I}$ be a J -frame with synthesis operator $T \in L(\ell_2(I), \mathcal{H})$. Then, its J -frame operator $S \in L(\mathcal{H})$ satisfies:*

1. $S = TT^\#$;
2. $S = S_+ - S_-$, where $S_+ := T_+ T_+^\#$ and $S_- := -T_- T_-^\#$ are J -positive operators;
3. S is an invertible J -selfadjoint operator;
4. $\text{ind}_\pm(S) = \dim \mathcal{H}_\pm$, where $\text{ind}_\pm(S)$ are the indices of S .

Proof. Proof If $\mathcal{F} = \{f_i\}_{i \in I}$ is a J -frame with synthesis operator $T \in L(\ell_2(I), \mathcal{H})$, then $T^\# f = \sum_{i \in I} \sigma_i [f, f_i] e_i$ for $f \in \mathcal{H}$. So,

$$TT^\# f = T \left(\sum_{i \in I} \sigma_i [f, f_i] e_i \right) = \sum_{i \in I} \sigma_i [f, f_i] f_i = Sf, \quad \text{for every } f \in \mathcal{H}.$$

Furthermore, if $I_\pm = \{i \in I : \pm [f_i, f_i] > 0\}$, consider $T_\pm = TP_\pm$ as usual. Then,

$$TT^\# = (T_+ + T_-)(T_+ + T_-)^\# = T_+ T_+^\# + T_- T_-^\# = T_+ T_+^\# - (-T_- T_-^\#),$$

because $T_+ T_-^\# = T_- T_+^\# = 0$. Therefore, $S = S_+ - S_-$ if $S_\pm := \pm T_\pm T_\pm^\#$. Notice that S_\pm is a J -positive operator because

$$S_\pm = \pm T_\pm T_\pm^\# = \pm T_\pm J_2 T_\pm^* J = T_\pm T_\pm^* J.$$

To prove the invertibility of S observe that, if $Sf = 0$ then $S_+ f = S_- f$. But $R(S_+) \cap R(S_-) \subseteq R(T_+) \cap R(T_-) = \{0\}$. Thus, S is injective. On the other hand, $R(S) = S(\mathcal{M}_+^{[\perp]}) + S(\mathcal{M}_-^{[\perp]})$ because $\mathcal{H} = \mathcal{M}_+^{[\perp]} \dot{+} \mathcal{M}_-^{[\perp]}$. But it is easy to see that $\mathcal{M}_\pm^{[\perp]} \subseteq N(S_\pm)$. So, $S(\mathcal{M}_\pm^{[\perp]}) = S_\mp(\mathcal{M}_\pm^{[\perp]})$ and $R(S) = S_- (\mathcal{M}_+^{[\perp]}) + S_+ (\mathcal{M}_-^{[\perp]}) = R(S_-) + R(S_+) = \mathcal{M}_+ + \mathcal{M}_- = \mathcal{H}$. Therefore, S is invertible.

Finally, the identities $\text{ind}_\pm(S) = \dim \mathcal{H}_\pm$ follow from the indices definition. Recall that if $A \in L(\mathcal{H})$ is a J -selfadjoint operator, $\text{ind}_+(A)$ is the supremum of all positive integers r such that there exists a positive invertible matrix of the form $([Ax_j, x_k])_{j,k=1,\dots,r}$, where $x_1, \dots, x_r \in \mathcal{H}$ (if no such r exists, $\text{ind}_+(A) = 0$). Similarly, $\text{ind}_-(A) = \text{ind}_+(-A)$ is the supremum of all positive integers m such that there exists a negative invertible matrix of the form $([Ay_j, y_k])_{j,k=1,\dots,m}$, where $y_1, \dots, y_m \in \mathcal{H}$, see [13].

Corollary 5.2. *Let $\mathcal{F} = \{f_i\}_{i \in I}$ be a J -frame for \mathcal{H} with J -frame operator $S \in L(\mathcal{H})$. Then, $R(S_\pm) = \mathcal{M}_\pm$ and $N(S_\pm) = \mathcal{M}_\pm^{[\perp]}$. Furthermore, if $Q = P_{\mathcal{M}_+ // \mathcal{M}_-}$,*

$$S_+ = QSQ^\# \quad \text{and} \quad S_- = -(I - Q)S(I - Q)^\#. \quad (26)$$

Proof. Recall that $S_+ := T_+ T_+^\# = T_+(J_2 T_+^* J) = T_+ T_+^* J$. Then, $R(S_+) = R(T_+ T_+^* J) = R(T_+ T_+^*) = R(T_+) = \mathcal{M}_+$ because $R(T_+)$ is closed. Since S_+ is J -selfadjoint, it follows that $N(S_+) = R(S_+)^{\perp} = \mathcal{M}_+^{\perp}$. Analogously, $R(S_-) = \mathcal{M}_-$ and $N(S_-) = \mathcal{M}_-^{\perp}$.

Since $S = S_+ - S_-$, if $Q = P_{\mathcal{M}_+ // \mathcal{M}_-}$ then

$$QS = Q(S_+ - S_-) = S_+,$$

by the characterization of the range and nullspace of S_+ . Therefore, $SQ^\# = QS = QSQ^\#$. Analogously, $S(I - Q)^\# = (I - Q)S = (I - Q)S(I - Q)^\#$.

The above corollary states that S is the diagonal block operator matrix

$$S = \begin{pmatrix} S_+ & 0 \\ 0 & -S_- \end{pmatrix}, \quad (27)$$

according to the (oblique) decompositions $\mathcal{H} = \mathcal{M}_-^{\perp} \dot{+} \mathcal{M}_+^{\perp}$ and $\mathcal{H} = \mathcal{M}_+ \dot{+} \mathcal{M}_-$ of the domain and codomain of S , respectively.

5.1 The indefinite reconstruction formula associated to a J -frame

Given a J -frame $\mathcal{F} = \{f_i\}_{i \in I}$ with synthesis operator T , there is a duality between \mathcal{F} and the frame $\mathcal{G} = \{g_i\}_{i \in I}$ given by $g_i = S^{-1}f_i$: if $f \in \mathcal{H}$,

$$f = SS^{-1}f = TT^\#(S^{-1}f) = T\left(\sum_{i \in I} \sigma_i[S^{-1}f, f_i]e_i\right) = \sum_{i \in I} \sigma_i[S^{-1}f, f_i]f_i = \sum_{i \in I} \sigma_i[f, S^{-1}f_i]f_i.$$

Analogously,

$$f = S^{-1}Sf = S^{-1}(TT^\#f) = S^{-1}\left(\sum_{i \in I} \sigma_i[f, f_i]f_i\right) = \sum_{i \in I} \sigma_i[f, f_i]S^{-1}f_i.$$

Therefore, for every $f \in \mathcal{H}$, there is an *indefinite reconstruction formula* associated to \mathcal{F} :

$$f = \sum_{i \in I} \sigma_i[f, g_i]f_i = \sum_{i \in I} \sigma_i[f, f_i]g_i. \quad (28)$$

The following question arises naturally: is $\mathcal{G} = \{S^{-1}f_i\}_{i \in I}$ also a J -frame for \mathcal{H} ?

Proposition 5.3. *If $\mathcal{F} = \{f_i\}_{i \in I}$ is a J -frame for a Krein space \mathcal{H} with J -frame operator S , then $\mathcal{G} = \{S^{-1}f_i\}_{i \in I}$ is also a J -frame for \mathcal{H} .*

Proof. Proof Given a J -frame $\mathcal{F} = \{f_i\}_{i \in I}$ for \mathcal{H} with J -frame operator S , observe that the synthesis operator of $\mathcal{G} = \{S^{-1}f_i\}_{i \in I}$ is $V := S^{-1}T \in L(\ell_2(I), \mathcal{H})$. Furthermore, by Corollary 5.2, $S(\mathcal{M}_\pm^{\perp}) = \mathcal{M}_\pm$. Then, $S^{-1}(\mathcal{M}_\pm) = \mathcal{M}_\pm^{\perp}$ and it follows that

$$[S^{-1}f_i, S^{-1}f_i] > 0 \quad \text{if and only if} \quad [f_i, f_i] > 0.$$

Thus, $V_\pm = VP_\pm = S^{-1}T_\pm$ and $R(V_+)$ (resp. $R(V_-)$) is a maximal uniformly J -positive (resp. J -negative) subspace of \mathcal{H} . So, \mathcal{G} is a J -frame for \mathcal{H} .

If $\mathcal{F} = \{f_i\}_{i \in I}$ is a frame for a Hilbert space \mathcal{H} with synthesis operator $T \in L(\ell_2(I), \mathcal{H})$, then the family $\{(TT^*)^{-1}f_i\}_{i \in I}$ is called the *canonical dual frame* because it is a dual frame for \mathcal{F} (see Eq. (10)) and it has the following optimal property: Given $f \in \mathcal{H}$,

$$\sum_{i \in I} |\langle f, (TT^*)^{-1}f_i \rangle|^2 \leq \sum_{i \in I} |c_i|^2, \quad \text{whenever} \quad f = \sum_{i \in I} c_i f_i, \quad (29)$$

for a family $(c_i)_{i \in I} \in \ell_2(I)$. In other words, the above representation has the smallest ℓ_2 -norm among the admissible frame coefficients representing f (see [12]).

Remark 5.4. If $\mathcal{F} = \{f_i\}_{i \in I}$ is a J -frame for \mathcal{H} then $\mathcal{F}_\pm = \{f_i\}_{i \in I_\pm}$ is a frame for the Hilbert space $(\mathcal{M}_\pm, \pm[\cdot, \cdot])$. Furthermore, the frame operator associated to \mathcal{F}_+ is $S_+ = T_+ T_+^\#$ and its canonical dual frame is given by $\mathcal{G}_+ = \{S_+^{-1} f_i\}_{i \in I_+}$. Analogously, the frame operator associated to \mathcal{F}_- is $S_- = -T_- T_-^\#$ and its canonical dual frame is given by $\mathcal{G}_- = \{S_-^{-1} f_i\}_{i \in I_-}$.

Then, since $\mathcal{H} = \mathcal{M}_+ \dot{+} \mathcal{M}_-$, \mathcal{H} can be seen as the (outer) direct sum of the Hilbert spaces $(\mathcal{M}_+, [\cdot, \cdot])$ and $(\mathcal{M}_-, -[\cdot, \cdot])$, i.e. the inner product given by

$$\langle f, g \rangle_{\mathcal{F}} = [f_+, g_+] - [f_-, g_-], \quad f = f_+ + f_-, \quad g = g_+ + g_-, \quad f_+, g_+ \in \mathcal{M}_+, \quad f_-, g_- \in \mathcal{M}_-,$$

turns $(\mathcal{H}, \langle \cdot, \cdot \rangle_{\mathcal{F}})$ into a Hilbert space and the projection $Q = P_{\mathcal{M}_+ // \mathcal{M}_-}$ is selfadjoint in this Hilbert space. So, if $f \in \mathcal{H}$,

$$\begin{aligned} \sum_{i \in I} |[f, S^{-1} f_i]|^2 &= \sum_{i \in I_+} |[Qf, S_+^{-1} f_i]|^2 + \sum_{i \in I_-} |[(I - Q)f, S_-^{-1} f_i]|^2 \leq \\ &\leq \sum_{i \in I_+} |c_i^+|^2 + \sum_{i \in I_-} |c_i^-|^2, \end{aligned}$$

whenever $f_+ = Qf = \sum_{i \in I_+} c_i^+ f_i$ and $f_- = (I - Q)f = \sum_{i \in I_-} c_i^- f_i$, for families $(c_i^\pm)_{i \in I_\pm} \in \ell_2(I_\pm)$. Therefore,

$$\sum_{i \in I} |[f, S^{-1} f_i]|^2 \leq \sum_{i \in I} |c_i|^2,$$

whenever $f = \sum_{i \in I} c_i f_i$ for some $(c_i)_{i \in I} \in \ell_2(I)$. In other words, the J -frame $\mathcal{G} = \{S^{-1} f_i\}_{i \in I}$ is the canonical dual frame of \mathcal{F} in the Hilbert space $(\mathcal{H}, \langle \cdot, \cdot \rangle_{\mathcal{F}})$.

5.2 Characterizing the J -frame operators

In a Hilbert space \mathcal{H} , it is well known that every positive invertible operator $S \in L(\mathcal{H})$ can be realized as the frame operator of a frame $\mathcal{F} = \{f_i\}_{i \in I}$ for \mathcal{H} , see [16]. Indeed, if $\mathcal{B} = \{x_i\}_{i \in I}$ is an orthonormal basis of \mathcal{H} , consider $T : \ell_2(I) \rightarrow \mathcal{H}$ given by $T e_i = S^{1/2} x_i$ for $i \in I$. Then, for every $f \in \mathcal{H}$,

$$TT^* f = \sum_{i \in I} \left\langle f, S^{1/2} x_i \right\rangle S^{1/2} x_i = S^{1/2} \left(\sum_{i \in I} \left\langle S^{1/2} f, x_i \right\rangle x_i \right) = S f$$

Therefore, $\mathcal{F} = \{S^{1/2} x_i\}_{i \in I}$ is a frame for \mathcal{H} and its frame operator is given by S .

The following paragraphs are devoted to characterize the set of J -frame operators.

Theorem 5.5. *Let $S \in GL(\mathcal{H})$ be a J -selfadjoint operator acting on a Krein space \mathcal{H} with fundamental symmetry J . Then, the following conditions are equivalent:*

1. *S is a J -frame operator, i.e. there exists a J -frame \mathcal{F} with synthesis operator T such that $S = TT^\#$.*
2. *There exists a projection $Q \in \mathcal{Q}$ such that QS is J -positive and $(I - Q)S$ is J -negative.*
3. *There exist J -positive operators $S_1, S_2 \in L(\mathcal{H})$ such that $S = S_1 - S_2$ and $R(S_1)$ (resp. $R(S_2)$) is a uniformly J -positive (resp. J -negative) subspace of \mathcal{H} .*

Proof. Proof 1. \rightarrow 2. follows from Proposition 5.1 and Corollary 5.2.

2. \rightarrow 3.: If there exists a projection $Q \in \mathcal{Q}$ such that QS is J -positive and $(I - Q)S$ is J -negative, consider the J -positive operators $S_1 = QS$ and $S_2 = -(I - Q)S$. Then, $S = S_1 - S_2$ and, by hypothesis, $R(S_1) = R(Q)$ is uniformly J -positive and $R(S_2) = R(I - Q) = N(Q)$ is uniformly J -negative.

3. \rightarrow 1.: Suppose that there exist J -positive operators $S_1, S_2 \in L(\mathcal{H})$ such that $S = S_1 - S_2$ and $R(S_1)$ (resp. $R(S_2)$) is a uniformly J -positive (resp. J -negative) subspace of \mathcal{H} . Denoting $\mathcal{K}_j = R(S_j)$ for $j = 1, 2$, observe that $A_j = S_j J|_{\mathcal{K}_j} \in GL(\mathcal{K}_j)^+$. Therefore, there exists a frame $\mathcal{F}_j = \{f_i\}_{i \in I_j} \subset \mathcal{K}_j$ for \mathcal{K}_j such that $A_j = T_j T_j^*$ if $T_j \in L(\ell_2(I_j), \mathcal{K}_j)$ is the synthesis operator of \mathcal{F}_j , for $j = 1, 2$.

Then, consider $\ell_2(I) := \ell_2(I_1) \oplus \ell_2(I_2)$ and $T \in L(\ell_2(I), \mathcal{H})$ given by

$$Tx = T_1x_1 + T_2x_2, \quad \text{if } x \in \ell_2(I), x = x_1 + x_2, x_j \in \ell_2(I_j) \text{ for } j = 1, 2.$$

It is easy to see that T is the synthesis operator of the frame $\mathcal{F} = \mathcal{F}_1 \cup \mathcal{F}_2$. Furthermore \mathcal{F} is a J -frame such that $I_+ = I_1$ and $I_- = I_2$.

Finally, endow $\ell_2(I)$ with the indefinite inner product defined by the diagonal operator $J_2 \in L(\ell_2(I))$ given by

$$J_2 e_i = \sigma_i e_i,$$

where $\sigma_i = 1$ if $i \in I_1$ and $\sigma_i = -1$ if $i \in I_2$. Notice that $T_1J_2 = T_1$ and $T_2J_2 = -T_2$. Furthermore, $T_1T_2^* = T_2T_1^* = 0$ because $R(T_2^*) = N(T_2)^\perp \subseteq \ell_2(I_1)^\perp = \ell_2(I_2) \subseteq N(T_1)$. Thus,

$$TT^\# = TJ_2T^*J = (T_1 + T_2)(T_1^* - T_2^*)J = T_1T_1^*J - T_2T_2^*J = A_1J - A_2J = S_1 - S_2 = S.$$

Given a J -frame $\mathcal{F} = \{f_i\}_{i \in I}$ for \mathcal{H} with J -frame operator $S \in L(\mathcal{H})$, it follows from Corollary 5.2 that

$$S(\mathcal{M}_-^{[\perp]}) = \mathcal{M}_+ \quad \text{and} \quad S(\mathcal{M}_+^{[\perp]}) = \mathcal{M}_-. \quad (30)$$

i.e. S maps a maximal uniformly J -positive (resp. J -negative) subspace into another maximal uniformly J -positive (resp. J -negative) subspace. The next proposition shows under which hypotheses the converse holds.

Proposition 5.6. *Let $S \in GL(\mathcal{H})$ be a J -selfadjoint operator. Then, S is a J -frame operator if and only if the following conditions hold:*

1. *there exists a maximal uniformly J -positive subspace \mathcal{T} of \mathcal{H} such that $S(\mathcal{T})$ is also maximal uniformly J -positive;*
2. *$[Sf, f] \geq 0$ for every $f \in \mathcal{T}$;*
3. *$[Sg, g] \leq 0$ for every $g \in S(\mathcal{T})^{[\perp]}$.*

Proof. Proof If S is a J -frame operator, consider $\mathcal{T} = \mathcal{M}_-^{[\perp]}$ which is a maximal uniformly J -positive subspace of \mathcal{H} . Then, $S(\mathcal{T}) = \mathcal{M}_+$ is also maximal uniformly J -positive. Furthermore,

$$[Sf, f] = [SQ^\#f, Q^\#f] = [QSQ^\#f, f] = [S_+f, f] \geq 0 \quad \text{for every } f \in \mathcal{T},$$

where $Q = P_{\mathcal{M}_+//\mathcal{M}_-}$. Also, $S(\mathcal{T})^{[\perp]} = \mathcal{M}_+^{[\perp]} = N(Q^\#) = R((I - Q)^\#)$. So,

$$[Sg, g] = [S(I - Q)^\#g, (I - Q)^\#g] = [(I - Q)S(I - Q)^\#g, g] = [-S_-g, g] \leq 0 \quad \text{for every } g \in S(\mathcal{T})^{[\perp]}.$$

Conversely, suppose that there exists a maximal uniformly J -positive subspace \mathcal{T} satisfying the hypothesis. Let $\mathcal{M} = S(\mathcal{T})$, which is maximal uniformly J -positive. Then, consider $Q = P_{\mathcal{M}//\mathcal{T}^{[\perp]}}$. It is well defined because $\mathcal{T}^{[\perp]}$ is maximal uniformly J -negative, see [2, Corollary 1.5.2]. Moreover, $Q \in \mathcal{Q}$.

Notice that $R(S(I - Q)^\#) = S(\mathcal{M}^{[\perp]}) = S(S(\mathcal{T})^{[\perp]}) = S(S^{-1}(\mathcal{T}^{[\perp]})) = \mathcal{T}^{[\perp]}$. Therefore, $QS(I - Q)^\# = 0$ and

$$QS = QSQ^\# + QS(I - Q)^\# = QSQ^\#.$$

Furthermore, if $[Sf, f] \geq 0$ for every $f \in \mathcal{T}$ then QS is J -positive. Analogously, if $[Sg, g] \leq 0$ for every $g \in S(\mathcal{T})^{[\perp]}$ then $(I - Q)S$ is J -negative. Then, by Theorem 5.5, S is a J -frame operator.

As it was proved in Proposition 5.1, if an operator $S \in L(\mathcal{H})$ is a J -frame operator then it is an invertible J -selfadjoint operator satisfying $\text{ind}_\pm(S) = \dim(\mathcal{H}_\pm)$. Unfortunately, the converse is not true.

Example 4. Consider the Krein space obtained by endowing \mathbb{C}^2 with the sesquilinear form

$$[(x_1, x_2), (y_1, y_2)] = x_1\overline{y_1} - x_2\overline{y_2},$$

and the invertible J -selfadjoint operator S , whose matrix in the standard orthonormal basis is given by

$$S = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix}.$$

Then, S satisfies $\text{ind}_\pm(S) = \dim(\mathcal{H}_\pm)$, but it maps each J -positive vector into a J -negative vector. Then, by Proposition 5.6, S cannot be a J -frame operator.

6 Final remarks

The following are some simple consequences of the material studied in the previous sections. Nevertheless, they are not going to be thoroughly developed in this notes.

Synthesis operators of J -frames as sums of plus and minus operators

If $\mathcal{F} = \{f_i\}_{i \in I}$ is a J -frame for the Krein space $(\mathcal{H}, [\cdot, \cdot])$, it is easy to see that T_+ and $T_+^\#$ are plus operators (considering $\ell_2(I)$ as a Krein space with the fundamental symmetry J_2 defined in (12)). Furthermore, $T_+^\#$ is strict, and, T_+ is a strict plus operator if and only if $N(T) \cap \ell_2(I_+) = \{0\}$.

Also, these conditions have a natural counterpart for the operators T_- and $T_-^\#$. Indeed, it follows analogously that T_- and $T_-^\#$ are minus operators; $T_-^\#$ is always strict, and, T_- is a strict minus operator if and only if $N(T) \cap \ell_2(I_-) = \{0\}$ (see [18, Ch. 2] for the terminology).

Frames for regular subspaces of a Krein space

Given a Krein space $(\mathcal{H}, [\cdot, \cdot])$, recall that a subspace \mathcal{S} of \mathcal{H} is *regular* if there exists a (unique) J -selfadjoint projection onto \mathcal{S} . Since a regular subspace \mathcal{S} , endowed with the restriction of the indefinite inner product $[\cdot, \cdot]$ to \mathcal{S} , is a Krein space (see [18, Ch. 1, Theorem 7.16]) the definition of J -frames applies for regular subspaces of \mathcal{H} too. Therefore, it is easy to infer a notion of “ J -frames for regular subspaces” of a Krein space.

References

- [1] N. I. Akhiezer and I. M. Glazman, Theory of Linear operators in Hilbert space, Dover Publ. Inc., 1993.
- [2] T. Ando, Linear operators on Krein spaces, Hokkaido University, Sapporo, Japan, 1979.
- [3] B.G. Bodmann and V.I. Paulsen, Frames, graphs and erasures, Linear Algebra Appl. 404 (2005) 118-146.
- [4] J. Bognár, Indefinite Inner Product Spaces, Springer-Verlag, 1974.
- [5] A. Buades, B. Coll and J.-M. Morel, Nonlocal image and movie denoising, Int. J. Comput. Vis. 76 (2008), no. 2, 123-140.
- [6] P. G. Casazza, The art of frame theory, Taiwanese J. Math. 4 (2000), no. 2, 129-201.
- [7] P. G. Casazza and O. Christensen, Frames containing a Riesz basis and preservation of this property under perturbations, SIAM J. Math. Anal. 29 (1998), no. 1, 266-278.
- [8] O. Christensen, An introduction to frames and Riesz bases, Applied and Numerical Harmonic Analysis, Birkhäuser, Boston, 2003.
- [9] O. Christensen, Recent Developments in Frame Theory, Modern Mathematical Models, Methods and Algorithms for Real World Systems. A.H. Siddiqi, I.S. Duff and O. Christensen (Editors), 2006, Anamaya Publishers, New Delhi, India.
- [10] F. Deutsch, The angle between subspaces of a Hilbert space, Approximation theory, wavelets and applications (Maratea, 1994), 107-130, NATO Adv. Sci. Inst. Ser. C Math. Phys. Sci., 454, Kluwer Acad. Publ., Dordrecht, 1995.
- [11] R. G. Douglas, On majorization, factorization and range inclusion of operators in Hilbert space, Proc. Amer. Math. Soc. 17 (1966), 413-416.
- [12] R. J. Duffin and A. C. Schaeffer, A class of nonharmonic Fourier series, Trans. Amer. Math. Soc. 72 (1952), 341-366.

- [13] M. A. Dritschel and J. Rovnyak, Operators on indefinite inner product spaces, Fields Institute Monographs no. 3, Amer. Math. Soc. Edited by Peter Lancaster 1996, 3, 141-232.
- [14] K. Esmeral García and E. Wagner, Frames in Krein spaces, preprint.
- [15] A. Grod, S. Kuzhel and V. Sudilovskaya, On operators of transition in Krein spaces, Opuscula Math. 31 (2010), no. 1, 49-59.
- [16] D. Han and D. R. Larson, Frames, bases and group representations, Mem. Amer. Math. Soc. 147 (2000), no. 697.
- [17] R.B. Holmes and V.I. Paulsen, Optimal frames for erasures, Linear Algebra Appl. 377 (2004), 31-51.
- [18] I. S. Iokhvidov and T. Ya. Azizov, Linear Operators in spaces with an indefinite metric, John Wiley and sons, 1989.
- [19] T. Kato, Perturbation theory for linear operators, Springer, New York, 1966.
- [20] M.A.S. Masoum, S. Jamali and N. Ghaffarzadeh, Detection and classification of power quality disturbances using discrete wavelet transform and wavelet networks, IET Sci. Meas. Technol. 4 (2010), 193–205.
- [21] I. Peng and S. Waldron, Signed frames and Hadamard products of Gram matrices, Linear Algebra Appl. 347 (2002), no. 1-3, 131-157.
- [22] T. Strohmer and R.W Heath Jr., Grassmannian frames with applications to coding and communication, Appl. Comput. Harmon. Anal. 14, (2003) 257-275.

Juan I. Giribet

jgiribet@fi.uba.ar

Departamento de Matemática, FI-UBA, Buenos Aires, Argentina
and
IAM-CONICET.

Alejandra Maestriperi

amaestri@fi.uba.ar

Departamento de Matemática, FI-UBA, Buenos Aires, Argentina
and
IAM-CONICET.

Francisco Martínez Pería

francisco@mate.unlp.edu.ar

Departamento de Matemática, FCE-UNLP, La Plata, Argentina
and
IAM-CONICET.

Pedro G. Massey

massey@mate.unlp.edu.ar

Departamento de Matemática, FCE-UNLP, La Plata, Argentina
and
IAM-CONICET, Saavedra 15, Piso 3, (1083) Buenos Aires, Argentina.