HYPERBOLICITY OF THE KARCHER MEAN

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ABSTRACT. The main concern of this paper is the Karcher mean of linearly independent triples (A, B, C) on the hyperboic manifold of 2×2 positive definite matrices of determinant 1. We show that the Karcher mean is of the form

$$\Lambda(A, B, C) = xA + y(B + C),$$
 $0 < x, y \text{ and } x + 2y < 1$

under the trace condition $\operatorname{tr}(AB^{-1})=\operatorname{tr}(AC^{-1})$. We further find an invertible hyperbolic matrix M depending only on the trace values $\operatorname{tr}(AB^{-1})$ and $\operatorname{tr}(BC^{-1})$ such that $\left[\begin{array}{c} x \\ y \end{array} \right]=M\left[\begin{array}{c} \cosh\theta \\ \sinh\theta \end{array} \right]$ for some (unique) $\theta\in\mathbb{R}$.

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1. Introduction and main results

The present paper is a continuation of the previous work regarding a closed form of the Karcher mean for 2×2 positive matrices triples [6, 8, 9].

Let \mathbb{P} be the set of 2×2 positive definite Hermitian matrices, which is a Cartan-Hadamard Riemannian manifold equipped with the trace metric $\delta(A, B) = ||\log A^{-1}B||_2$, where $||X||_2 = \sqrt{\operatorname{tr} X^* X}$ is the Frobenius norm. The Karcher mean of a triple $(A, B, C) \in \mathbb{P}^3$ is defined as

$$\Lambda(A, B, C) := \underset{X \in \mathbb{P}}{\operatorname{arg\,min}} \ (\delta^2(X, A) + \delta^2(X, B) + \delta^2(X, C))$$

and also as a unique positive definite solution of the Karcher equation

(1.1)
$$\log(X^{-1/2}AX^{-1/2}) + \log(X^{-1/2}BX^{-1/2}) + \log(X^{-1/2}CX^{-1/2}) = 0.$$

See [4, 5, 11, 10, 12, 13, 14, 15, 16, 17, 18] for more on the Riemannian trace metric and the Karcher mean.

Of special interest to us here is to find a closed-form expression of the Karcher mean $\Lambda(A, B, C)$. By joint homogeneity of the Karcher mean, this problem can be reduced to the hyperbolic manifold \mathbf{H}_2 of positive definite matrices of determinant 1. For $A, B \in \mathbf{H}_2$, the matrix geometric mean A and B defined by $A\#B := A^{1/2}(A^{-1/2}BA^{-1/2})^{1/2}A^{1/2}$ coincides with the geometric middle $\Lambda(A, B)$ between A and B and has the following linear form [1, 3]:

$$(1.2) A\#B = \frac{A+B}{\sqrt{\det(A+B)}}.$$

This together with Sturm's SLLN [19] and Holbrook's no dice theorem [10] provides a remarkable *linear* property of the Karcher mean on \mathbf{H}_2 :

(1.3)
$$\Lambda(A, B, C) = xA + yB + zC, \qquad x, y, z \ge 0.$$

The coefficients x, y, z are unique when the triple (A, B, C) is linearly independent in the Eucliden space of 2×2 Hermitian matrices. It is shown in [9] that

(1.4)
$$x = y = z = \frac{1}{\sqrt{\det(A + B + C)}}$$

under the trace condition $\operatorname{tr}(AB^{-1}) = \operatorname{tr}(AC^{-1}) = \operatorname{tr}(BC^{-1})$.

The main concern of this paper is the case of linearly independent triples $\{A, B, C\} \subset \mathbf{H}_2$ satisfying

(1.5)
$$\operatorname{tr}(AB^{-1}) = \operatorname{tr}(AC^{-1}),$$

which is equivalent to the isosceles property of the triangle of A, B, C in the hyperbolic manifold \mathbf{H}_2 ; $\overline{AB} = \overline{AC}$ (see Proposition 2.1).

The first main result in this paper is the following theorem.

Theorem 1.1. There exist unique positive real numbers x and y such that

(1.6)
$$\Lambda(A, B, C) = xA + yB + yC.$$

The key tool in the proof of Theorem 1.1 is the following unitary diagonalization of 2×2 positive definite matrix A:

(1.7)
$$A = U \begin{bmatrix} \cos \varphi & \sin \varphi \\ \sin \varphi & -\cos \varphi \end{bmatrix} \begin{bmatrix} \lambda & 0 \\ 0 & \beta \end{bmatrix} \begin{bmatrix} \cos \varphi & \sin \varphi \\ \sin \varphi & -\cos \varphi \end{bmatrix} U^*,$$

where λ, β are eigenvalues of A and U is a unitary diagonal matrix. The unitary diagonal matrix U and the CS matrix in (1.7), which is orthogonal and involutory, are obtained from the CS decomposition of 2×2 unitary matrices.

By invariance of the Karcher mean under permutations, (1.4) is immediate from Theorem 1.1. However, finding a closed form of x and y respectively is still problematic in general case. We will show that the coefficient vector (x, y, z = y) lies in a hyperboloid of two sheets determined by a and c;

$$(1.8) x^2 + y^2 + z^2 + 2axy + 2bxz + 2cyz = 1,$$

where $a = b := (1/2) \operatorname{tr}(AB^{-1})$ and $c := (1/2) \operatorname{tr}(BC^{-1})$, and that

$$(1.9) c+1 < \sqrt{c^2 + 8a^2} - 1 < 2a^2,$$

from which the following matrix depending on a and c

$$(1.10) M := \frac{1}{\sqrt{\xi}} \begin{bmatrix} \sqrt{\frac{\xi - c}{\xi + c + 2}} & -\sqrt{\frac{\xi + c}{\xi - c - 2}} \\ \frac{1}{\sqrt{2}}\sqrt{\frac{\xi + c}{\xi + c + 2}} & \frac{1}{\sqrt{2}}\sqrt{\frac{\xi - c}{\xi - c - 2}} \end{bmatrix}, \xi := \sqrt{c^2 + 8a^2}$$

is real with $\det M = \frac{1}{\sqrt{2(2a^2-c-1)}} > 0$ and $\operatorname{tr}(M) > 0$. In particular, all eigenvalues of M have positive real parts, that is, M is positively stable and hence is a hyperbolic matrix in the sense that all eigenvalues have non-zero real parts.

The second main result is the following.

Theorem 1.2. There exists a unique $\theta \in \mathbb{R}$ such that

Moreover.

$$(1.12) \quad \tanh\left(-\sqrt{\frac{(\xi+c)(\xi-c-2)}{(\xi-c)(\xi+c+2)}}\right) < \theta < \tanh\left(\sqrt{\frac{(\xi-c)(\xi-c-2)}{(\xi+c)(\xi+c+2)}}\right)$$

and

$$e^{\theta} = \frac{\sqrt{\xi}}{2} \frac{(2a^2 - c - 1)\left(\sqrt{x^2 + \frac{c+1}{2a^2 - c - 1}} - x\right)}{\sqrt{(\xi + c)(\xi + c + 2)} - \sqrt{(\xi - c)(\xi - c - 2)}}.$$

Invertibility of M ensures uniqueness of θ , called the *hyperbolic angle* of the Karcher mean $\Lambda(A, B, C)$. An alternative expression for M is presented in Section 3.

2. Proof of Theorem 1.1

We list some basic properties of matrices in \mathbf{H}_2 .

Proposition 2.1. Let $A, B, C \in \mathbf{H}_2$.

- (i) $tr(A) = tr(A^{-1})$, and tr(A) = tr(B) if and only if A and B have the same spectrum;
- (ii) $\det(A+B) = 2 + \operatorname{tr}(AB^{-1});$
- (iii) $\operatorname{tr}(AB^{-1}) \geq 2$, and $\operatorname{tr}(AB^{-1}) = 2$ if and only if A = B;
- (iv) For x, y, z > 0,

$$(x+y+z)^2 \le \det(xA+yB+zC)$$

= $x^2+y^2+z^2+xy\operatorname{tr}(AB^{-1})+xz\operatorname{tr}(AC^{-1})+yz\operatorname{tr}(BC^{-1}),$

and equality holds only when A = B = C.

Furthermore, the following are equivalent:

- (a) $tr(AB^{-1}) = tr(AC^{-1});$
- (b) $A^{-1/2}BA^{-1/2}$ and $A^{-1/2}CA^{-1/2}$ have the same spectrum;
- (c) $A^{-1/2}BA^{-1/2}$ and $A^{-1/2}CA^{-1/2}$ are unitary similar; and
- (d) $\delta(A, B) = \delta(A, C)$.

Proof. (i) is immediate from the fact that the map $x \mapsto x + x^{-1}$ is injective on $[1, \infty)$.

(ii) By a direct computation, $\det(I+X) = 1 + \det(X) + \operatorname{tr}(X)$ for every Hermitian matrix X. Then for $A, B, C \in \mathbb{P}$,

$$\det(A+B) = \det(A^{1/2}(I+A^{-1/2}BA^{-1/2})A^{1/2}) = \det(A)\det(I+A^{-1/2}BA^{-1/2})$$

$$= \det(A)\left(1+\det(A^{-1/2}BA^{-1/2})+\operatorname{tr}(A^{-1/2}BA^{-1/2})\right)$$

$$= \det(A)+\det(B)+\det(A)\operatorname{tr}(A^{-1}B).$$

Hence (ii) follows immediately.

(iii) Let λ be an eigenvalue of $A^{1/2}B^{-1}A^{1/2}$. Since $\det(A^{1/2}B^{-1}A^{1/2})=1$, λ^{-1} is an eigenvalue of $A^{1/2}BA^{1/2}=I$ and hence $\operatorname{tr}(AB^{-1})=\operatorname{tr}(A^{1/2}B^{-1}A^{1/2})=\lambda+\lambda^{-1}$. This implies that $\operatorname{tr}(AB^{-1})=\lambda+\lambda^{-1}\geq 2$, and that $\operatorname{tr}(AB^{-1})=2$ if and only if $\lambda=1$ if and only if A=B.

(iv) Using the determinant formula det(A+B) in the proof of (ii),

$$\det(A + B + C) = \det(A + B) + \det(C) + \det(C) \operatorname{tr}(C^{-1}(A + B))$$

$$= \det(A) + \det(B) + \det(C) + \det(A) \operatorname{tr}(A^{-1}B)$$

$$+ \det(C) (\operatorname{tr}(C^{-1}A) + \operatorname{tr}(C^{-1}B)).$$

This together with (i) implies that for $A, B, C \in \mathbf{H}_2$,

$$\det(xA + yB + zC) = x^2 + y^2 + z^2 + xy\operatorname{tr}(A^{-1}B) + xz\operatorname{tr}(C^{-1}A) + yz\operatorname{tr}(C^{-1}B)$$
$$= x^2 + y^2 + z^2 + xy\operatorname{tr}(AB^{-1}) + xz\operatorname{tr}(AC^{-1}) + yz\operatorname{tr}(BC^{-1}).$$

By the Minkowski's determinantal inequality,

$$\sqrt{\det(xA + yB + zC)} \ge \sqrt{\det(xA + yB)} + \sqrt{\det(zC)}$$

$$\ge \sqrt{\det(xA)} + \sqrt{\det(yB)} + \sqrt{\det(zC)}$$

$$= x + y + z.$$

Equality holds if and only if $zC = \alpha(xA + yB)$ and $yB = \beta(xA)$ for some positive α and β if and only if A = B = C from $\det(A) = \det(B) = \det(C) = 1$.

The equivalences between (a), (b) and (c) are straightforward from (i) and

$$\operatorname{tr}(AB^{-1}) = \operatorname{tr}(A^{1/2}B^{-1}A^{1/2}) = \operatorname{tr}(A^{-1/2}BA^{-1/2}) = \operatorname{tr}(A^{-1}B).$$

The equivalence between (a) and (d) appears in [9].

In the following, we let $\{A, B, C\} \subset \mathbf{H}_2$ be linearly independent. We have seen that

(2.13)
$$\Lambda(A, B, C) = xA + yB + zC$$

for some $x, y, z \ge 0$. We will first show that x, y, z are strictly positive by introducing a useful reduction on the triple $\{A, B, C\}$. Note that $A \ne B$ from linear independence. Let d > 1 be an eigenvalue of $A^{-1/2}BA^{-1/2}$. Pick a unitary matrix U such that

(2.14)
$$A^{-1/2}BA^{-1/2} = UDU^*, \quad D := \operatorname{diag}(d, d^{-1})$$

and set

$$(2.15) W = U^* A^{-1/2} C A^{-1/2} U.$$

Then the triple $\{I, D, W\}$ is linearly independent because the congruence transformation $X \mapsto A^{1/2}UXU^*A^{1/2}$ maps I, D, W to A, B, C respectively. In particular, W is not diagonal. Moreover,

$$(2.16) \operatorname{tr}(AB^{-1}) = \operatorname{tr}(D), \qquad \operatorname{tr}(AC^{-1}) = \operatorname{tr}(W), \qquad \operatorname{tr}(BC^{-1}) = \operatorname{tr}(DW^{-1}).$$

By invariancy under congruence transformations of the Karcher mean,

$$\begin{split} xA + yB + zC &= \Lambda(A, B, C) \\ &= \Lambda(A^{1/2}IA^{1/2}, A^{1/2}(A^{-1/2}BA^{-1/2})A^{1/2}, A^{1/2}(A^{-1/2}CA^{-1/2})A^{1/2}) \\ &= A^{1/2}\Lambda(I, UDU^*, A^{-1/2}CA^{-1/2})A^{1/2} \\ &= A^{1/2}\Lambda(I, UDU^*, UWU^*)A^{1/2} \\ &= A^{1/2}U\Lambda(I, D, W)U^*A^{1/2}. \end{split}$$

This implies that

(2.17)
$$\Lambda(I, D, W) = xI + yD + zW.$$

Linear independence of A, B, C plays a key role for positivity of x, y, z.

Proposition 2.2. The coefficients x, y, z are positive such that x + y + z < 1 and

(2.18)
$$\Lambda(A^{-1}, B^{-1}, C^{-1}) = xA^{-1} + yB^{-1} + zC^{-1}.$$

Proof. By Proposition 2.1 (iv), x + y + z < 1. To prove x, y, z > 0, it suffices to show $z \neq 0$ by permutation invariance of the Karcher mean. We may assume that A = I and B = D, a diagonal matrix, by the previous reduction process. Suppose that z = 0. By the Karcher equation,

$$0 = \log(xI + yD) + \log(xI + yD)D^{-1} + \log(xI + yD)^{1/2}C^{-1}(xI + yD)^{1/2}$$
$$= \log(xI + yD)^{2}D^{-1} + \log(xI + yD)^{1/2}C^{-1}(xI + yD)^{1/2}.$$

That is,

$$(xI + yD)^2D^{-1} = (xI + yD)^{-1/2}C(xI + yD)^{-1/2}$$

and hence $C = (xI + yD)^3D^{-1}$ is a diagonal matrix. This contradicts to linear independence of $\{I, D, C\}$.

To prove (2.18) we let $Z := xA^{-1} + yB^{-1} + zC^{-1}$. By Proposition 2.1 (iv),

$$\det(Z) = x^{2} + y^{2} + z^{2} + xy\operatorname{tr}(A^{-1}B) + xz\operatorname{tr}(A^{-1}C) + yz\operatorname{tr}(B^{-1}C)$$

$$= x^{2} + y^{2} + z^{2} + xy\operatorname{tr}(AB^{-1}) + xz\operatorname{tr}(AC^{-1}) + yz\operatorname{tr}(BC^{-1})$$

$$= \det(xA + yB + zC) = \det(\Lambda(A, B, C)) = 1.$$

By computing trace

$$tr[\Lambda(A, B, C)Z] = tr(xA + yB + zC)(xA^{-1} + yB^{-1} + zC^{-1})$$

$$= 2(x^2 + y^2 + z^2 + xy tr(AB^{-1}) + xz tr(AC^{-1}) + yz tr(BC^{-1}))$$

$$= 2.$$

By Proposition 2.1 (iii), $Z = \Lambda(A, B, C)^{-1}$ and hence

$$xA^{-1} + yB^{-1} + zC^{-1} = Z = \Lambda(A, B, C)^{-1} = \Lambda(A^{-1}, B^{-1}, C^{-1}).$$

Next, we shall show that y = z under the trace condition

$$\operatorname{tr}(AB^{-1}) = \operatorname{tr}(AC^{-1}),$$

equivalently $d + d^{-1} = \operatorname{tr}(D) = \operatorname{tr}(W)$, from (2.16). An important fact is that d > 1 is also an eigenvalue of the non-diagonal matrix W, which follows from the equivalence between (a) and (b) of Proposition 2.1. Let V be a unitary matrix such that $W = VDV^*$, unitary diagonalization of W. By CS-decomposition of V (cf. Theorem VII. 1. 6 of [2]),

$$V = V_1 \begin{bmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{bmatrix} V_2$$

for some unitary diagonal matrices V_1, V_2 and $0 \le \varphi < 2\pi$. It follows from $V_2 D V_2^* = D$ that

(2.19)
$$W = V_1 \begin{bmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{bmatrix} D \begin{bmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{bmatrix} V_1^*.$$

Set

$$R_{\varphi} := \begin{bmatrix} \cos \varphi & \sin \varphi \\ \sin \varphi & -\cos \varphi \end{bmatrix}.$$

Then R_{φ} is an orthogonal involutory matrix, that is,

$$R_{\varphi} = R_{\varphi}^T = R_{\varphi}^{-1}.$$

Since

$$\begin{bmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} \cos \varphi & \sin \varphi \\ \sin \varphi & -\cos \varphi \end{bmatrix},$$

we have from (2.19) that

$$(2.20) W = D_1 R_{\varphi} D R_{\varphi} D_1^*,$$

where $D_1 := V_1 \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ is a unitary diagonal matrix.

$$W_0 := R_{\varphi} D R_{\varphi}.$$

Then W_0 is not diagonal with determinant one, because W is not diagonal, and hence the triple $\{I, D, W_0\}$ is linearly independent. By Proposition 2.2, there exist positive reals x', y', z' such that

$$\Lambda(I, D, W_0) = x'I + y'D + z'W_0.$$

From the involutive property of the orthogonal matrix R_{ϑ} ,

$$\begin{split} x'I + y'D + z'W_0 &= \Lambda(I, D, W_0) = \Lambda(I, D, R_{\varphi}DR_{\varphi}) = \Lambda(I, R_{\varphi}DR_{\varphi}, D) \\ &= R_{\varphi}\Lambda(I, D, R_{\varphi}^TDR_{\varphi}^T)R_{\varphi} = R_{\varphi}\Lambda(I, D, R_{\varphi}DR_{\varphi})R_{\varphi} \\ &= R_{\varphi}\Lambda(I, D, W_0)R_{\varphi} \\ &= R_{\varphi}(x'I + y'D + z'W_0)R_{\varphi} = x'R_{\varphi}^2 + y'R_{\varphi}DR_{\varphi} + z'R_{\varphi}W_0R_{\varphi} \\ &= x'I + y'W_0 + z'R_{\varphi}^2DR_{\varphi}^2 = x'I + y'W_0 + z'D. \end{split}$$

By linearly independence, y' = z'.

Finally, by invariancy under permutations and congruence transformations of the Karcher mean and by the fact that D_1 is unitary diagonal,

$$xI + yD + zW = \Lambda (I, D, W) = \Lambda (I, D, D_1 R_{\varphi} D R_{\varphi} D_1^*)$$

$$= D_1 \Lambda (D_1^* D_1, D_1^* D D_1, R_{\varphi} D R_{\varphi}) D_1^*$$

$$= D_1 \Lambda (I, D, W_0) D_1^*$$

$$= D_1 (x'I + y'D + y'W_0) D_1^*$$

$$= x'D_1 D_1^* + y'D_1 D D_1^* + y'D_1 W_0 D_1^*$$

$$= x'I + y'D + y'W.$$

Again by linear independence,

$$x = x',$$
 $y = y',$ $z = y'.$

In particular, y = z. This completes the proof of Theorem 1.1.

The following is immediate by Theorem 1.1 and by permutation invariancy of the Karcher mean.

Corollary 2.3 ([9]). If $tr(AB^{-1}) = tr(AC^{-1}) = tr(BC^{-1})$, then

(2.21)
$$\Lambda(A, B, C) = \frac{A + B + C}{\sqrt{\det(A + B + C)}}.$$

For a triple $\{x, y, z\}$ in an inner product space,

$$(2.22) ||x - y|| = ||x - z|| \Longleftrightarrow ||m - y|| = ||m - z||, m := \frac{x + y + z}{3}$$

from
$$||x - 2y + z||^2 - ||x - 2z + y||^2 = 3(||x - y||^2 - ||x - z||^2)$$
.

The following is an appropriate version of (2.22); a property of the centroid of isosceles triangles on the hyperbolic manifold \mathbf{H}_2 .

Corollary 2.4. Let $A, B, C \in \mathbf{H}_2$ be linearly independent. If $\delta(A, B) = \delta(A, C)$, then $\delta(X, B) = \delta(X, C)$ for $X = \Lambda(A, B, C)$.

Proof. Suppose that $\delta(A, B) = \delta(A, C)$, that is, $\operatorname{tr}(AB^{-1}) = \operatorname{tr}(AC^{-1})$ by Proposition 2.1. By Theorem 1.1, $\Lambda(A, B, C) = xA + yB + yC$ for some positive x, y. Since

$$\begin{aligned} \operatorname{tr}(XB^{-1}) &= \operatorname{tr}(xAB^{-1} + yI + yCB^{-1}) = x \operatorname{tr}(AB^{-1}) + 2y + y \operatorname{tr}(CB^{-1}) \\ &= x \operatorname{tr}(AC^{-1}) + y \operatorname{tr}(BC^{-1}) + 2y = \operatorname{tr}(xAC^{-1} + yBC^{-1} + yI) \\ &= \operatorname{tr}(XC^{-1}), \end{aligned}$$

we have form Proposition 2.1 that $\delta(X, B) = \delta(X, C)$.

3. Proof of Theorem 1.2

Let $A, B, C \in \mathbf{H}_2$ be linearly independent and let x, y, z > 0 such that

$$\Lambda(A, B, C) = xA + yB + zC.$$

We shall introduce a quadratic surface containing the coefficient vector (x, y, z). By the determinantal identity of the Karcher mean,

$$1 = \det \Lambda(A, B, C) = \det(xA + yB + zC)$$

and by Proposition 2.1 (iv), x + y + z < 1 and

$$x^{2} + y^{2} + z^{2} + xy\operatorname{tr}(AB^{-1}) + xz\operatorname{tr}(AC^{-1}) + yz\operatorname{tr}(BC^{-1}) = 1.$$

Set

(3.23)
$$a = \frac{1}{2}\operatorname{tr}(AB^{-1}), \quad b = \frac{1}{2}\operatorname{tr}(AC^{-1}), \quad c = \frac{1}{2}\operatorname{tr}(BC^{-1}).$$

Then

$$(3.24) x^2 + y^2 + z^2 + 2axy + 2bxz + 2cyz = 1.$$

That is, the vector $(x, y, z) \in (0, 1)^3$ lies in the quadric surface determined by a, b, c. By Proposition 2.1 (iii),

$$(3.25) a, b, c > 1.$$

In terms of quadratic form, (3.24) can be written as

(3.26)
$$\mathbf{v}^T Q \mathbf{v} = 1, \qquad \mathbf{v}^T := (x, y, z)$$

where

$$Q = Q(A, B, C) := \begin{bmatrix} 1 & a & b \\ a & 1 & c \\ b & c & 1 \end{bmatrix}.$$

We note that the symmetric matrix Q depends only a, b, c, but the coefficient vector $\mathbf{v}^T = (x, y, z)$ depends on the Karcher mean $\Lambda(A, B, C)$. To determine the type of quadratic surface, we need to compute the inertia of Q. The characteristic polynomial $\det(Q - \lambda I)$ of Q is

$$(3.27) \qquad -\lambda^3 + 3\lambda^2 + (a^2 + b^2 + c^2 - 3)\lambda - (a^2 + b^2 + c^2) + 2abc + 1.$$

Let $\lambda_1 \leq \lambda_2 \leq \lambda_3$ be eigenvalues of Q = Q(A, B, C). Note that

$$(3.28) \lambda_1 + \lambda_2 + \lambda_3 = 3.$$

It is shown in [8] that by linear independency of $\{A, B, C\}$,

(3.29)
$$\det Q(A, B, C) = -(a^2 + b^2 + c^2) + 2abc + 1 > 0.$$

(One can restrict (A, B, C) to a linearly independent triple $(I, D, R_{\varphi}DR_{\varphi})$, where $D \neq I$ is diagonal, via the reduction process) By (3.25) and Sylvester's criterion on principal minors, Q is not positive semidefinite, that is, one of eigenvalues of Q is strictly negative. This together with (3.29) leads to

$$(3.30) \lambda_1 \le \lambda_2 < 0 < \lambda_3.$$

We then conclude that the quadratic surface (3.24) determined by a, b, c is a hyperboloid of two sheets.

Consider an orthogonal diagonalization of the symmetric matrix Q;

$$Q(A, B, C) = U^T \operatorname{diag}(\lambda_1, \lambda_2, \lambda_3) U.$$

Letting

$$\mathbf{w} = [w_1, w_2, w_3]^T := U\mathbf{v}$$

leads to

(3.31)
$$\mathbf{w}^T \operatorname{diag}(\lambda_1, \lambda_2, \lambda_3) \mathbf{w} = \lambda_1 w_1^2 + \lambda_2 w_2^2 + \lambda_3 w_3^2 = 1.$$

Using the parametric representation of a hyperboloid of two sheets,

$$w_1 = \frac{\sinh(u)\cosh(v)}{\sqrt{-\lambda_1}},$$

$$w_2 = \frac{\sinh(v)}{\sqrt{-\lambda_2}},$$

$$w_3 = \frac{\cosh(u)\cosh(v)}{\sqrt{\lambda_3}},$$

where $u, v \in \mathbb{R}$, one can see that the 3×3 real nonsingular matrix

(3.32)
$$K := U^T \operatorname{diag}\left(\frac{1}{\sqrt{-\lambda_1}}, \frac{1}{\sqrt{-\lambda_2}}, \frac{1}{\sqrt{\lambda_3}}\right)$$

satisfies

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = K \begin{bmatrix} \sinh(u)\cosh(v) \\ \sinh(v) \\ \cosh(u)\cosh(v) \end{bmatrix} = K \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} \cosh(u)\cosh(v) \\ \sinh(v) \\ \sinh(u)\cosh(v) \end{bmatrix}$$

for some $u, v \in \mathbb{R}$. Finding an explicit form of K in terms of a, b, c is equivalent to that of $\lambda_j, j = 1, 2, 3$.

It follows from $\lambda_1 + \lambda_2 + \lambda_3 = 3$ and $\det Q = \lambda_1 \lambda_2 \lambda_3$ that

$$\lambda_3 - 3 = -(\lambda_1 + \lambda_2) > 0$$

and

(3.34)
$$\lambda_1 = \frac{3 - \lambda_3 - \sqrt{(\lambda_3 - 3)^2 - 4\lambda_3^{-1}[-(a^2 + b^2 + c^2) + 2abc + 1]}}{2},$$

(3.35)
$$\lambda_2 = \frac{3 - \lambda_3 + \sqrt{(\lambda_3 - 3)^2 - 4\lambda_3^{-1}[-(a^2 + b^2 + c^2) + 2abc + 1]}}{2}.$$

Moreover,

$$(3.36) \quad \lambda_1 = \lambda_2 \iff \lambda_3^3 - 6\lambda_3^2 + 9\lambda_3 - 4[-(a^2 + b^2 + c^2) + 2abc + 1] = 0.$$

It is not easy to find an explicit form of λ_3 in terms of a, b, c. However, if two of a, b, c are equal, which is the case of our main concern, then we have an explicit form of the eigenvalues.

In the following we assume that a=b, that is, $\operatorname{tr}(AB^{-1})=\operatorname{tr}(AC^{-1})$. Then

(3.37)
$$\det Q = (c-1)(2a^2 - (1+c)).$$

It then follows from c > 1 and $\det Q > 0$ that

$$(3.38) 2a^2 > c + 1.$$

One can show directly that

$$\lambda_3 = \frac{c + 2 + \sqrt{c^2 + 8a^2}}{2}$$

and

$$\{\lambda_1, \lambda_2\} = \left\{1 - c, \frac{c + 2 - \sqrt{c^2 + 8a^2}}{2}\right\}.$$

Furthermore,

$$(3.39) \lambda_1 = \lambda_2 \Longleftrightarrow a(=b) = c,$$

and

(3.40)
$$\lambda_1 = \begin{cases} 1 - c, & \text{if } a = b \le c \\ \frac{c + 2 - \sqrt{c^2 + 8a^2}}{2}, & \text{if } a = b > c. \end{cases}$$

Set

$$\xi = \xi(A, B, C) := \sqrt{c^2 + 8a^2}.$$

By (3.38),

and (1.9) holds true. By a direct computation, the real matrix M in Theorem 1.2

(3.42)
$$M := \begin{bmatrix} \sqrt{\frac{\xi - c}{\xi(\xi + c + 2)}} & -\sqrt{\frac{\xi + c}{\xi(\xi - c - 2)}} \\ \sqrt{\frac{\xi + c}{2\xi(\xi + c + 2)}} & \sqrt{\frac{\xi - c}{2\xi(\xi - c - 2)}} \end{bmatrix}$$

is nonsingular with

$$\det M = \frac{1}{\sqrt{2(2a^2 - c - 1)}} = \frac{\sqrt{c - 1}}{\sqrt{2 \det Q}} > 0.$$

Proof of Theorem 1.2.

By Theorem 1.1, y = z. That is, $\mathbf{v} = (x, y, y)^T$.

Set

(3.43)
$$\alpha := \sqrt{1 - \frac{c}{\sqrt{c^2 + 8a^2}}}, \qquad \beta := \sqrt{1 + \frac{c}{\sqrt{c^2 + 8a^2}}}.$$

Then

(3.44)
$$\alpha^2 + \beta^2 = 2, \qquad \alpha\beta = \sqrt{\frac{8a^2}{c^2 + 8a^2}}.$$

Case 1: $a = b \le c$. In this case,

$$\lambda_1 = 1 - c \le \lambda_2 = \frac{c + 2 - \sqrt{c^2 + 8a^2}}{2} \le \lambda_3 = \frac{c + 2 + \sqrt{c^2 + 8a^2}}{2}.$$

From $\lambda_3 - \lambda_2 = \sqrt{c^2 + 8a^2}$ and $\lambda_1 + \lambda_2 + \lambda_3 = 3$, we have

$$\alpha = \sqrt{1 - \frac{1 - \lambda_1}{\lambda_3 - \lambda_2}} = \sqrt{\frac{\lambda_3 - \lambda_2 + \lambda_1 - 1}{\lambda_3 - \lambda_2}} = \sqrt{\frac{2(1 - \lambda_2)}{\lambda_3 - \lambda_2}},$$

$$\beta = \sqrt{1 + \frac{1 - \lambda_1}{\lambda_3 - \lambda_2}} = \sqrt{\frac{\lambda_3 - \lambda_2 - \lambda_1 + 1}{\lambda_3 - \lambda_2}} = \sqrt{\frac{2(\lambda_3 - 1)}{\lambda_3 - \lambda_2}}.$$

Let

$$U := \begin{bmatrix} 0 & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}}\beta & \frac{1}{2}\alpha & \frac{1}{2}\alpha \\ \frac{1}{\sqrt{2}}\alpha & \frac{1}{2}\beta & \frac{1}{2}\beta \end{bmatrix}.$$

By (3.43),

$$UU^{T} = \begin{bmatrix} 0 & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}}\beta & \frac{1}{2}\alpha & \frac{1}{2}\alpha \\ \frac{1}{\sqrt{2}}\alpha & \frac{1}{2}\beta & \frac{1}{2}\beta \end{bmatrix} \begin{bmatrix} 0 & -\frac{1}{\sqrt{2}}\beta & \frac{1}{\sqrt{2}}\alpha \\ -\frac{1}{\sqrt{2}} & \frac{1}{2}\alpha & \frac{1}{2}\beta \\ \frac{1}{\sqrt{2}} & \frac{1}{2}\alpha & \frac{1}{2}\beta \end{bmatrix}$$
$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2}(\alpha^{2} + \beta^{2}) & 0 \\ 0 & 0 & \frac{1}{2}(\alpha^{2} + \beta^{2}) \end{bmatrix} = I.$$

It follows from

(3.45)
$$\alpha \beta = \sqrt{\frac{8a^2}{c^2 + 8a^2}} = \frac{2\sqrt{2}a}{\lambda_3 - \lambda_2}$$

and

(3.46)
$$\lambda_2 \beta^2 + \lambda_3 \alpha^2 = 2, \quad \lambda_2 \alpha^2 + \lambda_3 \beta^2 = 4 - 2\lambda_1 > 0$$

that for $T := \operatorname{diag}(\lambda_1, \lambda_2, \lambda_3)$,

$$U^T T U = \begin{bmatrix} \frac{\lambda_2 \beta^2 + \lambda_3 \alpha^2}{2} & \frac{\alpha \beta}{2\sqrt{2}} (\lambda_3 - \lambda_2) & \frac{\alpha \beta}{2\sqrt{2}} (\lambda_3 - \lambda_2) \\ \frac{\alpha \beta}{2\sqrt{2}} (\lambda_3 - \lambda_2) & \frac{\lambda_2 \alpha^2 + \lambda_3 \beta^2}{4} + \frac{\lambda_1}{2} & \frac{\lambda_2 \alpha^2 + \lambda_3 \beta^2}{4} - \frac{\lambda_1}{2} \\ \frac{\alpha \beta}{2\sqrt{2}} (\lambda_3 - \lambda_2) & \frac{\lambda_2 \alpha^2 + \lambda_3 \beta^2}{4} - \frac{\lambda_1}{2} & \frac{\lambda_2 \alpha^2 + \lambda_3 \beta^2}{4} + \frac{\lambda_1}{2} \end{bmatrix} = Q.$$

Letting

$$\mathbf{w} = [w_1, w_2, w_3]^T := U\mathbf{v}$$

leads to

(3.47)
$$\mathbf{w}^T T \mathbf{w} = \lambda_1 w_1^2 + \lambda_2 w_2^2 + \lambda_3 w_3^2 = 1.$$

From

$$\mathbf{v} = \begin{bmatrix} x \\ y \\ y \end{bmatrix} = U^T \mathbf{w} = \begin{bmatrix} 0 & -\frac{1}{\sqrt{2}}\beta & \frac{1}{\sqrt{2}}\alpha \\ -\frac{1}{\sqrt{2}} & \frac{1}{2}\alpha & \frac{1}{2}\beta \\ \frac{1}{\sqrt{2}} & \frac{1}{2}\alpha & \frac{1}{2}\beta \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix},$$

we have that

$$w_1 = 0$$

and

(3.48)
$$x = \frac{1}{\sqrt{2}}(\alpha w_3 - \beta w_2), \qquad y = \frac{1}{2}(\alpha w_2 + \beta w_3).$$

By (3.47),

(3.49)
$$w_2 = \frac{\sinh \theta}{\sqrt{-\lambda_2}}, \quad w_3 = \frac{\cosh \theta}{\sqrt{\lambda_3}}$$

for some $\theta \in \mathbb{R}$. Hence

$$(3.50) \quad \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -\frac{\beta}{\sqrt{-2\lambda_2}} & \frac{\alpha}{\sqrt{2\lambda_3}} \\ \frac{\alpha}{2\sqrt{-\lambda_2}} & \frac{\beta}{2\sqrt{\lambda_3}} \end{bmatrix} \begin{bmatrix} \sinh \theta \\ \cosh \theta \end{bmatrix} = \begin{bmatrix} \frac{\alpha}{\sqrt{2\lambda_3}} & -\frac{\beta}{\sqrt{-2\lambda_2}} \\ \frac{\beta}{2\sqrt{\lambda_3}} & \frac{\alpha}{2\sqrt{-\lambda_2}} \end{bmatrix} \begin{bmatrix} \cosh \theta \\ \sinh \theta \end{bmatrix}.$$

One can see that

$$\begin{bmatrix} \frac{\alpha}{\sqrt{2\lambda_3}} & -\frac{\beta}{\sqrt{-2\lambda_2}} \\ \frac{\beta}{2\sqrt{\lambda_3}} & \frac{\alpha}{2\sqrt{-\lambda_2}} \end{bmatrix} = M.$$

This shows existence of θ . Uniqueness is direct from invertibility of M.

Since x, y > 0, we get from (3.50) that

$$\tanh^{-1}\left(\frac{\alpha}{\beta}\frac{\sqrt{-\lambda_2}}{\sqrt{\lambda_3}}\right) > \theta$$

and

$$\theta > \tanh^{-1}\left(-\frac{\beta}{\alpha}\frac{\sqrt{-\lambda_2}}{\sqrt{\lambda_3}}\right).$$

That is,

(3.51)
$$\tanh^{-1}\left(-\frac{\beta}{\alpha}\frac{\sqrt{-\lambda_2}}{\sqrt{\lambda_3}}\right) < \theta < \tanh^{-1}\left(\frac{\alpha}{\beta}\frac{\sqrt{-\lambda_2}}{\sqrt{\lambda_3}}\right).$$

The upper and lower bounds are same with that of (1.12).

Note that

$$x = \frac{\alpha}{\sqrt{2\lambda_3}} \cosh \theta - \frac{\beta}{\sqrt{-2\lambda_2}} \sinh \theta,$$

equivalently,

$$e^{2\theta} \left(\frac{\alpha}{\sqrt{2\lambda_3}} - \frac{\beta}{\sqrt{-2\lambda_2}} \right) - 2xe^{\theta} + \frac{\alpha}{\sqrt{2\lambda_3}} + \frac{\beta}{\sqrt{-2\lambda_2}} = 0.$$

From (3.46), we have that

$$\frac{\alpha}{\sqrt{2\lambda_3}} < \frac{\beta}{\sqrt{-2\lambda_2}},$$

and hence

$$e^{\theta} = \frac{x \pm \sqrt{x^2 - \left(\frac{\alpha}{\sqrt{2\lambda_3}} - \frac{\beta}{\sqrt{-2\lambda_2}}\right) \left(\frac{\alpha}{\sqrt{2\lambda_3}} + \frac{\beta}{\sqrt{-2\lambda_2}}\right)}}{\frac{\alpha}{\sqrt{2\lambda_3}} - \frac{\beta}{\sqrt{-2\lambda_2}}}$$
$$= \frac{x \pm \sqrt{x^2 - \left(\frac{\alpha^2}{2\lambda_3} + \frac{\beta^2}{2\lambda_2}\right)}}{\frac{\alpha}{\sqrt{2\lambda_3}} - \frac{\beta}{\sqrt{-2\lambda_2}}} = \frac{x \pm \sqrt{x^2 + \frac{\lambda_1 - 2}{\lambda_2 \lambda_3}}}{\frac{\alpha}{\sqrt{2\lambda_3}} - \frac{\beta}{\sqrt{-2\lambda_2}}},$$

where the last equality follows from (3.46). As $\lambda_1 - 2$ is negative and $\lambda_2 \lambda_3$ is negative,

$$\sqrt{x^2 + \frac{\lambda_1 - 2}{\lambda_2 \lambda_3}} > \sqrt{x^2} = x$$

and hence

$$x + \sqrt{x^2 + \frac{\lambda_1 - 2}{\lambda_2 \lambda_3}} > 0, \quad x - \sqrt{x^2 + \frac{\lambda_1 - 2}{\lambda_2 \lambda_3}} < 0.$$

This implies that

$$e^{\theta} = \frac{x - \sqrt{x^2 + \frac{\lambda_1 - 2}{\lambda_2 \lambda_3}}}{\frac{\alpha}{\sqrt{2\lambda_3}} - \frac{\beta}{\sqrt{-2\lambda_2}}} = \frac{\sqrt{\xi}}{2} \frac{(2a^2 - c - 1)\left(\sqrt{x^2 + \frac{c + 1}{2a^2 - c - 1}} - x\right)}{\sqrt{(\xi + c)(\xi + c + 2)} - \sqrt{(\xi - c)(\xi - c - 2)}}.$$

Case 2. a = b > c. In this case,

$$\lambda_1 = \frac{c + 2 - \sqrt{c^2 + 8a^2}}{2} \le \lambda_2 = 1 - c \le \lambda_3 = \frac{c + 2 + \sqrt{c^2 + 8a^2}}{2}.$$

Set

$$V := \begin{bmatrix} -\frac{1}{\sqrt{2}}\beta & \frac{1}{2}\alpha & \frac{1}{2}\alpha \\ 0 & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}}\alpha & \frac{1}{2}\beta & \frac{1}{2}\beta \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} U.$$

Then $V^TV = VV^T = I$ and for $T := diag(\lambda_1, \lambda_2, \lambda_3)$,

$$V^T T V = \begin{bmatrix} \frac{\lambda_1 \beta^2 + \lambda_3 \alpha^2}{2} & \frac{\alpha \beta}{2\sqrt{2}} (\lambda_3 - \lambda_1) & \frac{\alpha \beta}{2\sqrt{2}} (\lambda_3 - \lambda_1) \\ \frac{\alpha \beta}{2\sqrt{2}} (\lambda_3 - \lambda_1) & \frac{\lambda_1 \alpha^2 + \lambda_3 \beta^2}{4} + \frac{\lambda_2}{2} & \frac{\lambda_1 \alpha^2 + \lambda_3 \beta^2}{4} - \frac{\lambda_2}{2} \\ \frac{\alpha \beta}{2\sqrt{2}} (\lambda_3 - \lambda_1) & \frac{\lambda_1 \alpha^2 + \lambda_3 \beta^2}{4} - \frac{\lambda_2}{2} & \frac{\lambda_1 \alpha^2 + \lambda_3 \beta^2}{4} + \frac{\lambda_2}{2} \end{bmatrix} = Q.$$

Set $\mathbf{u} = (u_1, u_2, u_3)^T =: V \mathbf{v}$. Then $\mathbf{u}^T T \mathbf{u} = \lambda_1 u_1^2 + \lambda_2 u_2^2 + \lambda_3 u_3^2 = 1$ and

$$\mathbf{v} = \begin{bmatrix} x \\ y \\ y \end{bmatrix} = V^T \mathbf{u} = \begin{bmatrix} -\frac{1}{\sqrt{2}}\beta & 0 & \frac{1}{\sqrt{2}}\alpha \\ \frac{1}{2}\alpha & -\frac{1}{\sqrt{2}} & \frac{1}{2}\beta \\ \frac{1}{2}\alpha & \frac{1}{\sqrt{2}} & \frac{1}{2}\beta \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}$$

Hence $u_2 = 0$ and

$$x = \frac{1}{\sqrt{2}}(\alpha u_3 - \beta u_1), \qquad y = \frac{1}{2}(\alpha u_1 + \beta u_3).$$

There exists θ^* such that

$$u_1 = \frac{\sinh \theta^*}{\sqrt{-\lambda_1}}, \quad u_3 = \frac{\cosh \theta^*}{\sqrt{\lambda_3}}.$$

As Case 1, we get that

(3.52)
$$\tanh^{-1}\left(-\frac{\beta}{\alpha}\frac{\sqrt{-\lambda_1}}{\sqrt{\lambda_3}}\right) < \theta^* < \tanh^{-1}\left(\frac{\alpha}{\beta}\frac{\sqrt{-\lambda_1}}{\sqrt{\lambda_3}}\right)$$

and

(3.53)
$$\begin{cases} x = \frac{\alpha}{\sqrt{2\lambda_3}} \cosh \theta^* - \frac{\beta}{\sqrt{-2\lambda_1}} \sinh \theta^*, \\ y = \frac{\beta}{2\sqrt{\lambda_3}} \cosh \theta^* + \frac{\alpha}{2\sqrt{-\lambda_1}} \sinh \theta^*. \end{cases}$$

The remaining part of proof is similar to Case 1. This completes the proof of Theorem 1.2.

In terms of eigenvalues $\lambda_1 \leq \lambda_2 < \lambda_3$ of Q = Q(A, B, C), we have the following alternative expression of x and y.

Corollary 3.1. If $a = b \le c$, there exists unique $\theta \in \mathbb{R}$ such that

(3.54)
$$\begin{bmatrix} x \\ y \end{bmatrix} = \frac{1}{\sqrt{\lambda_3 - \lambda_2}} \begin{bmatrix} \sqrt{\frac{1 - \lambda_2}{\lambda_3}} & -\sqrt{\frac{1 - \lambda_3}{\lambda_2}} \\ \sqrt{\frac{\lambda_3 - 1}{2\lambda_3}} & \sqrt{\frac{\lambda_2 - 1}{2\lambda_2}} \end{bmatrix} \begin{bmatrix} \cosh \theta \\ \sinh \theta \end{bmatrix}.$$

In particular,

$$\tanh^{-1}\left(-\sqrt{\frac{\lambda_2(1-\lambda_3)}{\lambda_3(1-\lambda_2)}}\right) < \theta < \tanh^{-1}\left(\sqrt{\frac{\lambda_2(\lambda_2-1)}{\lambda_3(\lambda_3-1)}}\right).$$

If a = b > c, then there exists unique θ such that

(3.55)
$$\left[\begin{array}{c} x \\ y \end{array} \right] = \frac{1}{\sqrt{\lambda_3 - \lambda_1}} \left[\begin{array}{ccc} \sqrt{\frac{1 - \lambda_1}{\lambda_3}} & -\sqrt{\frac{1 - \lambda_3}{\lambda_1}} \\ \sqrt{\frac{\lambda_3 - 1}{2\lambda_3}} & \sqrt{\frac{\lambda_1 - 1}{2\lambda_1}} \end{array} \right] \left[\begin{array}{c} \cosh \theta \\ \sinh \theta \end{array} \right].$$

In particular,

$$\tanh^{-1}\left(-\sqrt{\frac{\lambda_1(1-\lambda_3)}{\lambda_3(1-\lambda_1)}}\right) < \theta < \tanh^{-1}\left(\sqrt{\frac{\lambda_1(\lambda_1-1)}{\lambda_3(\lambda_3-1)}}\right).$$

Remark 3.2. Note from [9] and (3.39) that x = y if and only if a = b = c if and only if $\lambda_1 = \lambda_2$, in which case, $x = y = \frac{1}{\sqrt{\det(A+B+C)}}$. Suppose that a = b = c. Then $\xi = 3a$ and

$$\alpha = \sqrt{\frac{2}{3}}, \qquad \beta = \frac{2}{\sqrt{3}}, \qquad \lambda_1 = \lambda_2 = 1 - a, \qquad \lambda_3 = 2a + 1.$$

It then follows from (3.50) that $\theta = 0$ and

$$x = y = \frac{1}{\sqrt{3\lambda_3}} = \frac{1}{\sqrt{3(2a+1)}} = \frac{1}{\sqrt{\det(A+B+C)}}.$$

Moreover,

$$M = \frac{1}{\sqrt{3}} \begin{bmatrix} \frac{1}{\sqrt{2a+1}} & -\frac{\sqrt{2}}{\sqrt{a-1}} \\ \frac{1}{\sqrt{2a+1}} & \frac{1}{\sqrt{2(a-1)}} \end{bmatrix}.$$

Question. Does $\theta = 0$ a necessary condition for a = b = c?

Remark 3.3. Note that for a = b, (3.24) becomes

$$(3.56) x^2 + 2y^2 + 4axy + 2cy^2 = 1,$$

alternatively, $x^2 + (y')^2 + kxy' = 1$, where $y' := \sqrt{2(1+c)}y$ and $k := \frac{4a}{\sqrt{2(1+c)}} > 2$.

Setting
$$\begin{bmatrix} u \\ v \end{bmatrix} := \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y' \end{bmatrix}$$
 yields $\left(\frac{k}{2} + 1\right) u^2 - \left(\frac{k}{2} - 1\right) v^2 = 1$. It follows from $k > 2$ that

$$u = \frac{1}{\sqrt{\frac{k}{2} + 1}} \cosh t, \qquad v = \frac{1}{\sqrt{\frac{k}{2} - 1}} \sinh t$$

for some $t \in \mathbb{R}$. That is,

$$x = \frac{1}{\sqrt{k+2}} \cosh(t) - \frac{1}{\sqrt{k-2}} \sinh(t),$$

$$y' = \frac{1}{\sqrt{k+2}} \cosh(t) + \frac{1}{\sqrt{k-2}} \sinh(t)$$

and hence

$$\begin{bmatrix} x \\ y \end{bmatrix} = N \begin{bmatrix} \cosh(t) \\ \sinh(t) \end{bmatrix}, \qquad N := \begin{bmatrix} \frac{1}{\sqrt{k+2}} & -\frac{1}{\sqrt{k-2}} \\ \frac{1}{\sqrt{2(1+c)(k+2)}} & \frac{1}{\sqrt{2(1+c)(k-2)}} \end{bmatrix}.$$

The N is also hyperbolic. The following shows that the matrix M is much better than N. Suppose that a = b = c. By the preceding remark, $\theta = 0$. Solving

$$\left[\begin{array}{c} \cosh \theta \\ \sinh \theta \end{array}\right] = M^{-1} N \left[\begin{array}{c} \cosh(t) \\ \sinh(t) \end{array}\right]$$

yields

$$t = \tanh^{-1} \left(-\frac{\frac{1}{\sqrt{2}}\sqrt{\frac{4a}{4a+2}}\frac{1}{\sqrt{k+2}} + \sqrt{\frac{2a}{4a+2}}\frac{1}{\sqrt{2(1+a)(k+2)}}}{\frac{1}{\sqrt{2}}\sqrt{\frac{4a}{4a+2}}\frac{1}{\sqrt{k-2}} + \sqrt{\frac{2a}{4a+2}}\frac{1}{\sqrt{2(1+a)(k-2)}}} \right).$$

Example 3.4. Let

$$D = \frac{1}{100} \begin{bmatrix} 101 + \sqrt{201} & 0 \\ 0 & 101 - \sqrt{201} \end{bmatrix}, \quad W = \frac{101}{20100} \begin{bmatrix} 201 + \sqrt{201} & \sqrt{\frac{151}{10050}} \frac{20100}{101} \\ \sqrt{\frac{151}{10050}} \frac{20100}{101} & 201 - \sqrt{201} \end{bmatrix}.$$

Note that $tr(D) = tr(W) = tr(WD^{-1}) = 2.02$ and det(D) = det(W) = 1, so that a = 1.01. By the previous remark,

$$M = \frac{1}{\sqrt{3}} \begin{bmatrix} \frac{1}{\sqrt{2.02+1}} & -\frac{\sqrt{2}}{\sqrt{1.01-1}} \\ \frac{1}{\sqrt{2.02+1}} & \frac{1}{\sqrt{2}(1.01-1)} \end{bmatrix} = \frac{1}{\sqrt{3}} \begin{bmatrix} \frac{1}{\sqrt{3.02}} & -\frac{\sqrt{2}}{\sqrt{0.01}} \\ \frac{1}{\sqrt{3.02}} & \frac{1}{\sqrt{0.02}} \end{bmatrix}.$$

The matrix M has positive real eigenvalues; $\lambda_1(M) \approx 1.31099 < \lambda_2(M) \approx 3.10372$. Using the Matrix Means Toolbox by Bini and Iannazzo for MATLAB we can see numerically that $\Lambda(I, D, W) \approx \begin{bmatrix} 1.0723 & 0.0409 \\ 0.0409 & 0.9310 \end{bmatrix}$ and $x \approx 0.3273, y \approx 0.3336, \theta \approx 0.000603531$.

Example 3.5. Let

$$D = \begin{bmatrix} 18 + \sqrt{323} & 0 \\ 0 & \frac{1}{18 + \sqrt{323}} \end{bmatrix}, \quad W = \begin{bmatrix} 18 + \frac{321}{\sqrt{323}} & 2\sqrt{\frac{322}{323}} \\ 2\sqrt{\frac{322}{323}} & 18 - \frac{321}{\sqrt{323}} \end{bmatrix}.$$

Then $a=b=\frac{\operatorname{tr}(D)}{2}=\frac{\operatorname{tr}(W)}{2}=18, c=\frac{\operatorname{tr}(DW^{-1})}{2}=3, \xi=\sqrt{c^2+8a^2}=51,$ and

$$M = \frac{1}{\sqrt{51}} \begin{bmatrix} \sqrt{\frac{48}{56}} & -\sqrt{\frac{54}{46}} \\ \frac{1}{\sqrt{2}}\sqrt{\frac{54}{56}} & \frac{1}{\sqrt{2}}\sqrt{\frac{48}{46}} \end{bmatrix} = \frac{1}{\sqrt{51}} \begin{bmatrix} \sqrt{\frac{6}{7}} & -\sqrt{\frac{27}{23}} \\ \frac{1}{\sqrt{2}}\sqrt{\frac{27}{28}} & \frac{1}{\sqrt{2}}\sqrt{\frac{24}{23}} \end{bmatrix}.$$

It has complex eigenvalues; $\lambda(M) \approx 0.115393 \pm 0.120617i$. Numerically, $\Lambda(I, D, W) \approx \begin{bmatrix} 9.8980 & 0.2728 \\ 0.2728 & 0.1085 \end{bmatrix}$, and $x \approx 0.0855, y \approx 0.1366, \theta \approx 0.332439$.

We closed this section with a sufficient condition on the linearly independent triples (A, B, C) in \mathbb{P} satisfying

$$\Lambda(A, B, C) = xA + y(B + C).$$

Let (A, B, C) be a linearly independent triple in \mathbb{P} . Set

$$A_0 = \frac{A}{\sqrt{\det(A)}}, \quad B_0 = \frac{B}{\sqrt{\det(B)}}, \quad C_0 = \frac{C}{\sqrt{\det(C)}}.$$

Assume that $\operatorname{tr}(A_0B_0^{-1}) = \operatorname{tr}(A_0C_0^{-1})$, equivalently

(3.57)
$$\frac{\operatorname{tr}(AB^{-1})}{\operatorname{tr}(AC^{-1})} = \sqrt{\det(B^{-1}C)}.$$

By Theorem 1.1, there exist unique positive real numbers x_0, y_0 such that $\Lambda(A_0, B_0, C_0) = x_0 A_0 + y_0 B_0 + y_0 C_0$ and hence by the determinantal identity for the Karcher mean

$$\Lambda(A, B, C) = \det(ABC)^{\frac{1}{6}} \Lambda(A_0, B_0, C_0) = \det(ABC)^{\frac{1}{6}} (x_0 A_0 + y_0 B_0 + y_0 C_0)
= \det(A^{-2}BC)^{\frac{1}{6}} x_0 A + \det(AB^{-2}C)^{\frac{1}{6}} y_0 B + \det(ABC^{-2})^{\frac{1}{6}} y_0 C.$$

Setting

$$x := \det(A^{-2}BC)^{\frac{1}{6}}x_0, \qquad y := \det(AB^{-2}C)^{\frac{1}{6}}y_0, \qquad z := \det(ABC^{-2})^{\frac{1}{6}}y_0$$

yields $\Lambda(A, B, C) = xA + yB + zC$. We note that y = z if and only if $\det(B) = \det(C)$, in which case $\operatorname{tr}(AB^{-1}) = \operatorname{tr}(AC^{-1})$ from (3.57).

Corollary 3.6. For every linearly independent triple (A, B, C) in \mathbb{P} satisfying $\det(B) = \det(C)$ and $\operatorname{tr}(AB^{-1}) = \operatorname{tr}(AC^{-1})$,

$$\Lambda(A, B, C) = xA + y(B + C)$$

for some positive real numbers x, y.

4. Final remarks

Let A, B, C be linearly independent 2×2 positive definite matrices of determinant 1, and let $a = \frac{1}{2}\operatorname{tr}(AB^{-1}), b = \frac{1}{2}\operatorname{tr}(AC^{-1}), c = \frac{1}{2}\operatorname{tr}(BC^{-1})$. By Proposition 2.1, there exist unique positive real numbers x, y, z such that $\Lambda(A, B, C) = xA + yB + zC$. One can see that the ALM mean [1] is also linearly representable in the sense that $\operatorname{Alm}(A, B, C) = x'A + y'B + z'C$ for some unique nonnegative real numbers x', y', z'. Similarly for the BMP mean [7]. This raises the question whether every matrix geometric mean admits a linear representation or not. It is known only by numerical tests that the coefficient vectors (x, y, z) and (x', y', z') are different, alternatively $\Lambda(A, B, C) \neq \operatorname{Alm}(A, B, C)$ for general (A, B, C), a standing open problem after the Karcher mean was appeared [4]. We list some related open problems including that of finding a closed-form of x and y, under a = b, and of finding a geometric meaning of the hyperbolic angle θ of the Karcher mean.

1. By [9], a = b = c if and only if x = y = z. Does the trace condition a = b a necessary and sufficient condition for y = z?

- 2. The Karcher equation in this paper is involved only for positivity of x, y, z. One can see that y' = z' when a = b. Does the coefficients x', y', z' are all positive?
- 3. The invertible matrix M in (1.11) depends only on a = b, c. One can show that Theorem 1.2 holds for the ALM mean:

$$\left[\begin{array}{c} x'\\ y' \end{array}\right] = M \left[\begin{array}{c} \cosh \theta'\\ \sinh \theta' \end{array}\right]$$

for some (unique) θ' . If $\theta \neq \theta'$, then $\Lambda(A, B, C) \neq \text{Alm}(A, B, C)$. Let D = diag(2, 1/2) and $W = \begin{bmatrix} \frac{3}{4} & \frac{\sqrt{5}}{4} \\ \frac{\sqrt{5}}{4} & \frac{7}{4} \end{bmatrix}$. Then $\text{tr}(D) = \text{tr}(W) = \frac{5}{2}, \text{tr}(DW^{-1}) = \frac{31}{8}$ and

$$\mathrm{Alm}(I,D,W) = \begin{bmatrix} 1.0865 & 0.1595 \\ 0.1595 & 0.9438 \end{bmatrix} \neq \Lambda(I,D,W) = \begin{bmatrix} 1.0863 & 0.1592 \\ 0.1592 & 0.9439 \end{bmatrix}.$$

In this case

$$M \approx \begin{bmatrix} 0.2553 & -2.3494 \\ 0.3047 & 1.6613 \end{bmatrix},$$

and $\theta \approx -0.0197, \theta' \approx -0.0203$.

4. Some properties of the real matrix K in (3.32), like hyperbolicity or negative stability, are clearly of interest for further work.

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